

Gripping Technology and Automation Technology

Product overview

Hand-in-hand for tomorrow





More
than
Standard components

11,000



Awards



60 95%

Apprentices &
Students per year

Retention rate



Employees

Sustainability



C_oLab

Planning and implementation of industrial
automation and robotics applications



1945

Founded by Friedrich Schunk in a garage



Hand in hand for tomorrow

Shaping the future with innovative technologies – that is the claim of Schunk. To this end, the experienced automation and production specialist is pushing the further development and digitalization of its product and service portfolio in order to make industrial processes more efficient, transparent and sustainable. The family-owned company with headquarters in Lauffen/Nekar is a global leader in toolholding and workholding, gripping technology and automation technology. Approximately 3,500 employees in 9 plants and 34 directly owned subsidiaries and distribution partners in more than 50 countries throughout the world ensure an intensive market presence.

Benefit from the SCHUNK modular system with over 4,000 standard components

For any robot, for any industry, for any
handling task.



SCHUNK sets standards in all industries world-wide with its components and gripper portfolio. Our robot accessories include a uniquely comprehensive standard range of modules for the mechanical, sensory, and power connection of handling devices and robots. The comprehensive range of robust and long-lasting grippers for small components and

universal grippers features high product quality, precision, and numerous monitoring options. What's more, SCHUNK's Handling solutions of axis system open up new perspectives for cost and benefit-optimized automation solutions from a single source.



Applications



Gripping technology



Automation technology

Content

	Page
Applications	6
E-Mobility	8
Life Science	10
Robots & cobots	12
Application kits	14
Gripping technology	16
Pneumatic grippers	18
Electric grippers	30
Adhesive grippers	34
Magnetic grippers	36
Accessories	38
Automation technology	44
Swivel units	46
Linear modules	52
Change systems & feed-through modules	62
Rotary feed-throughs	68
Compensation units & collision protection	70
Force/torque sensors	76
Machining tools	80

Applications from SCHUNK: Easily implement projects with us

No matter what challenge you are facing in your manufacturing process – with SCHUNK you have the right partner at your side. We create individual concepts for your gripping applications, handling and clamping tasks and take care of their validation in our CoLabs. Thanks to our holistic approach, you benefit from reduced interfaces, and we also take over the design and project planning of your application and thus noticeably relieve your day-to-day project work. Another advantage is our in-house production, which is characterized by a high level of vertical integration, reliable process monitoring, and complete assembly documentation.



E-Mobility

SCHUNK is your reliable partner for production's challenges in e-mobility.



Life science

Coordinated product portfolios from SCHUNK meet the high manufacturing standards in the life science sector.



Robots & cobots

SCHUNK offers an extensive program of modules for mechanical, sensory and energetic connection of handling devices, robots and cobots.



Application kits

With its MHS application kits and 2D-gripping systems, others easy-to-integrate packages for automated gripping, clamping and clamping, as well as for gripping and placing of non-position-critical workpieces.



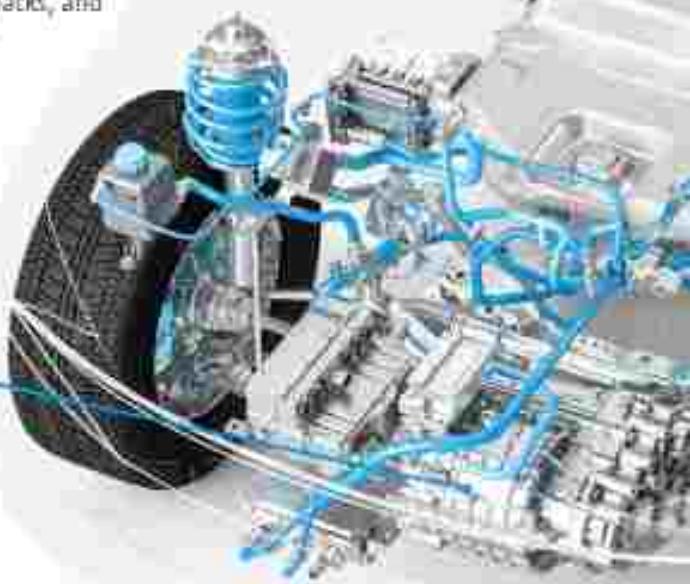
E-Mobility



SCHUNK is your reliable partner for production's changeover to e-mobility. We are an automation specialist and competence leader for toolholding and workholding, gripping technology and automation technology and supply you with everything from axis systems to robot accessories from a single source. Through the clever combination of our standard products, we always find an individually suitable solution for you. You will benefit from our many years of engineering know-how in the industry. SCHUNK products are already known by all well-known automotive manufacturers and their suppliers. This accelerates integration into new process chains enormously and keeps you in the fast lane from the very beginning when switching to e-mobility.

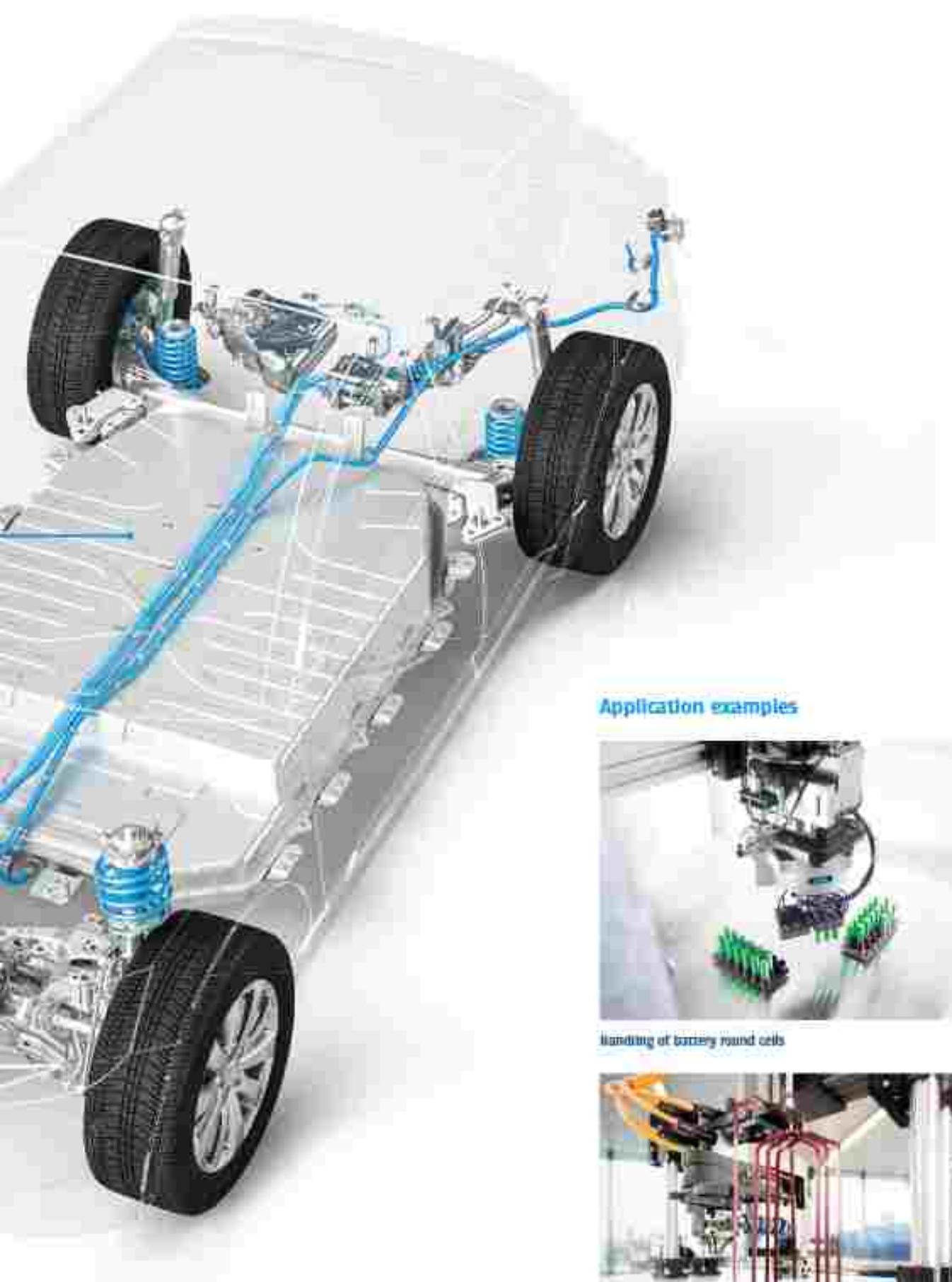
Battery systems

Using batteries brings new challenges to the automotive industry. SCHUNK supports you in all aspects: Starting with cell production with requirements for cleanroom and dry room environments as well as short cycle times, then on to handling sensitive components during assembly into battery modules and packs, and all the way to final assembly in the vehicle.

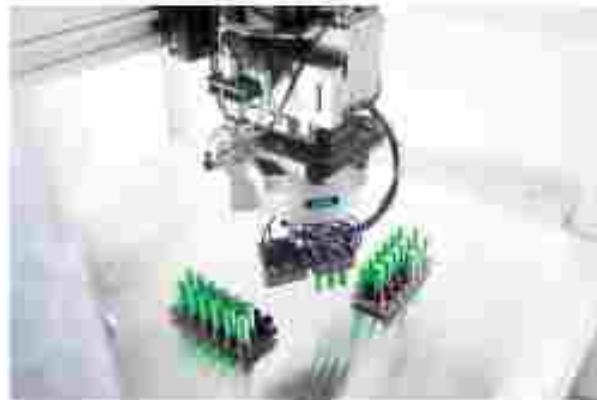


Electric drives

We are at the forefront of every step in the production and assembly of e-drives. Regardless of whether it concerns the specific setting of the hairpins, the handling of the sheet metal packages or the assembly of the components to the finished e-axis – SCHUNK can support you. Thereby we take special process requirements into account, such as flexibility due to the many different hairpins, precision and dynamics for very short cycle times, and maximum reliability for a long service life of the system.



Application examples



Handling of battery round cells



Rollpin handling

Life Science



Life science brings together biotechnology, medical technology, and pharmaceuticals. This multidisciplinary collaboration leads to the development of new medical technology products, treatment methods, and medicines. The manufacturing industry plays a key role here – manufacturing uses modern processes for producing high-quality products in the sectors of medical technology, lab automation, and pharmaceuticals. Coordinated product portfolios from SCHUNK meet the strict requirements for manufacturing quality and reliability.



MedTech

Process-reliable manufacturing in medical technology

SCHUNK supplies the manufacturers of medical technology systems in the manufacturing industry of medical products and puts its focus on robustness and absolute process reliability.



Lab automation

Efficient and reliable laboratory processes

SCHUNK supplies numerous ideal components for laboratory equipment and handling systems for lab automation.



Pharma Cleanroom-compatible performance booster

With cleanroom-compatible and customized solutions in a hygiene-friendly design, SCHUNK enables the handling of sensitive and high-quality pharmaceutical products.

Application examples



Automated handling and preparation of pharmaceuticals



Handling and holding of blood collection tubes



Exact force measurement in rehabilitation



Micro-handling for medical technology

Robots & Cobots



By using robots and cobots, companies can increase their productivity and efficiency, enhance the quality of their products, and relieve their employees at work. However, with new application scenarios and applications, new challenges are involved. To meet these demands, we work closely with leading robot manufacturers. By building know-how, it allows us to offer a wide range of end-of-arm solutions tailored to the specific requirements of your applications and various robot manufacturers and their models. For example, our software modules enable the smooth interaction of components and robots.



Application examples



Loading of a machine tool with a joined-arm robot



Handling of electronic assembly groups with a SCARA robot



Pick&Place application with a Delta robot

- Applications with industrial robots and cobots are available on schunk.com/robots-cobots
- Gripping technology for industrial robots and cobots are available starting on page 16
- Toolholding and workholding for tools and workpieces are available on schunk.com
- Automation technology such as quick-change systems are available starting on page 44

Application kit MTB

Diverse automation scenarios can now be implemented in no time and with minimal effort. With its MTB application kits, SCHUNK offers easy-to-integrate packages for automated gripping, clamping and changing of workpieces. Components that are well matched to one another, down to the very last detail, merge seamlessly into the machine environment. The kits are equally suitable for automation beginners and professionals.



Easy to automate

Process reliability

By means of a sealed valve box, the electronic system is protected against dust, chips, and oil.

Increased productivity

This is achieved by automated removal of chips and coolant from the workpiece and clamping force block.

Productivity boost

The double gripper kit enables workpiece removal and reloading of the machine in one robot cycle.

Space-saving: single gripper kit

For an easy entry into automated machine loading. Perfect in confined spaces.



Effective:

double gripper kit

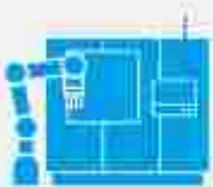
Loading and unloading in just one cycle. Optimized cycle times for increasing machine productivity.



Reliable:

Clamping force block kit

The interplay between the grippers and the automated clamping force block increases productivity of the metal cutting machine.



Robot connection package for gripper and clamping force block

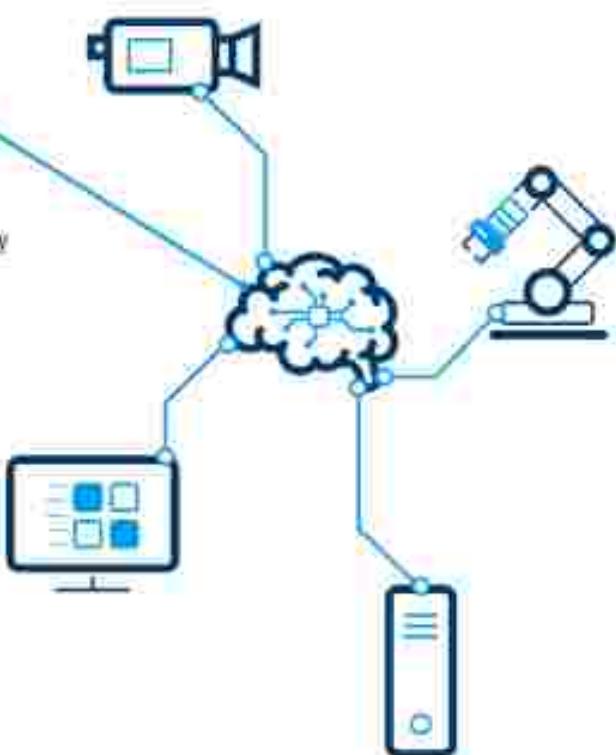
For quick and seamless integration. Available as standard for a variety of cobots from different manufacturers.

2D Grasping kit

The perfectly matched application kit for gripping and placing non-position-oriented workpieces consists of a camera system and lens, an application-specific gripping system, SCHUNK's own industrial PC (SVC), as well as a plug-in for easy integration into the robot control system. The core of the system is the AI software developed by SCHUNK, which reliably ensures recognition, even under changing light conditions.

Vision-based gripping

- **Easy teach-in of components**
No prior knowledge of image processing system programming necessary
- **Automated gripping planning**
The software can determine gripping points independently
- **Integrated collision protection**
Automated calculation of interfering contours of fingers and workpiece
- **Intelligent software**
The software adapts itself to non-optimal lighting conditions and changing backgrounds
- **Application validation**
Risk reduction and easier commissioning due to application validation in the SCHUNK Colab



Gripper variety made by SCHUNK: Your requirements are our motivation



SCHUNK offers the world's most comprehensive portfolio of grippers. Standard grippers, ready-to-install assembly groups, and customized gripping technology solutions for your handling and assembly, automation and robot end-of-arm applications. We always meet the most complicated gripping requirements, and we solve them. The result: Robust and durable gripping solutions which have ensured reliability in systems and machines all over the world for 30 years.



Grippers for Small components

Grippers for handling small, light, and sensitive workpieces



Universal grippers

Grippers for a wide range of applications



Long-stroke grippers

Grippers with long jaw stroke and high gripping force

Pneumatic grippers

Pneumatic grippers from SCHUNK have stood for high quality and reliability for many years. The focus is always on your workplace. From small to large, from round to square, for every batch size and every applicable environment.



Pneumatic grippers

Electric grippers

For the requirements of modern process flows, electric gripper solutions offer many advantages. In modern process flows, our electric grippers enjoy advantages such as application flexibility and process feedback.



Electric grippers

Adhesive grippers

The biotonically inspiring Adhesive gripper technology is based on the principle of adhesion and uses biomimetically acting Van der Waals forces to handle without workpiece.



Adhesive grippers

Magnetic grippers

SCHUNK's magnetic grippers move ferromagnetic components in any position and size.



Magnetic grippers

Accessories

To match the gripper type, SCHUNK offers accessories for each kind of application and handling requirement - and also in extreme conditions.

Accessories

Pneumatic grippers



Tech

The more demanding your application, the more precise the performance of the pneumatic gripper should match the task at hand. With our Tech segment, you have a whole range of "specialists" at your disposal, such as grippers for handling O-rings, gears, or rims.

Premium

In the premium segment you will find grippers of the highest quality with a wide range of variants and options. In addition to more robust grippers, we also offer more maintenance-free gripping cycles and long service life.

Parallel gripper

Tech

- Process specialists
- Maximum service life
- Best performance data



KTG

MPC-plus

Premium

- Best performance data
- Maximum service life
- Up to 26 months warranty
- Wide range of variants and matching accessories



MPC-plus

MPC-plus-P

Economy

- Proven SÜDLINK quality at attractive conditions
- Robust performance
- Maximum economic efficiency



MPC

JGP-P

Economy

In our Economy segment, the focus is not only on performance, but also on economic efficiency: You get real SCHUNK quality under attractive conditions. Optimized for all standard applications in clean environments. The grippers focus on the essential characteristics, and thus ensure efficient use in operation.

The power of our pneumatic grippers

- Proven
- Long service life
- Versatile
- High-quality

Ceramic grippers



PSR



08G



PZS-plus



PZS-plus+

Angular/torsional gripper



SAP



08G



PZS



PZT



PZS-plus



PZS-plus+



SWG



PZC



SGT



SGB

2-finger parallel gripper

Pneumatic grippers

2-finger parallel gripper

Product

Grippers for small components

MPC-grips

PGG

Industrial grippers

PGM-grips-2

PGI-grips-2



Description

Powerful, compact gripper for small components with smooth-running roller guide system at the base jaws.

For small to medium-sized workpieces.

Areas of application:
Assembly, testing, laboratory, universally applicable pharmaceutical, food

Narrow gripper with long stroke of up to 60 mm per finger

For light to medium weight workpieces

Areas of application:
Universally applicable

Guaranteed maintenance-free universal gripper with powerful gripping force and high maximum moment

For light to heavy workpieces

Areas of application:
Universally applicable

Universal grippers with a long jaw stroke, integrated sensor system and high maximum moment

Handle handling of a wide range of parts

Areas of application: Different applications in sheet as well as strip environments

Advantages

Maximum gripping force with even pressure distribution

Precise gripping thanks to the minimal play junction roller guide

Tood-tightening lubrication

High maximum moment due to the robust T-slot guidance

Direct power transmission and high efficiency thanks to pneumatic 3-piston drive concept

Workpiece is clamped centrally using a platen-cage principle

Power handling due to robust multi-touch guidances

Use of long gripper fingers

Process reliability and extended maintenance intervals thanks to permanent lubrication

Secure, constant gripping force, maintenance-free

Precise and process-reliable monitoring of the complete gripper series via IO-DIN thanks to the integrated sensor system

IP 65 DIN protected as standard

Technical data

Number of fingers	2	7	11	5
Gripping force [N]	1 ... 270	45 ... 540	180 ... 27000	145 ... 1900
Stroke per jaw [mm]	1 ... 10	10 ... 60	2 ... 45	30 ... 75
Weight [kg]	0.03 ... 0.33	0.09 ... 1.2	0.08 ... 29.3	0.48 ... 7.9
Recommended workpiece weight [kg]	0 ... 12%	0 ... 7.7	0 ... 97.5	0 ... 7
Closing/opening time [s]	0.01 ... 0.006/0.01 ... 0.08	0.02 ... 0.28/0.03 ... 0.25	0.07 ... 0.8/0.07 ... 0.8	0.03 ... 0.25 / 0.03 ... 0.75
Max. permissible finger length [mm]	50	160	400	260 ... 268
Response accuracy [mm]	0.07	up to 0.02	up to 0.03	0.03
Protection class IP	30/54	44	40/64	54/67
Dimensions EN 60 1666-1	—	—	—	—
Sensor system	++	+	+++	++
High number of variants	++	++	+++	++

Working conditions

Clean	●	●	●	●
Consumable/nonsolid dust	○	○	●	●
Consumable/dust and liquids	—	—	—	—
Consumable/aggressive liquids	—	—	—	—
High-temperature range > 90 °C	●	○	●	●
Dust/dust	●	○	●	●

● = very highly suitable

○ = medium-sized selection

● = Highly suitable

○ = Wide selection

● = Suitable in customized version

+++ = Very wide selection

Long-jaw grippers

PG1

PG2

Tech

Grippers for small components

PG3

Mechanical grippers

PG4



Grippers with high maximum moments and a long jaw stroke

Compressible long-jaw gripper with high gripping force and profiled rail guide

Gripper for small components with sensor base

Universal robotic gripper with high gripping force and high extraction moments and sensor base

For large workpieces and/or a wide range of parts

For very large workpieces and/or a wide range of parts

For small to medium-sized workplaces

For small to medium-sized workplaces

Areas of application: Mechanical and plant engineering, assembly and handling, automotive

Areas of application: Individually configurable for the application site

Areas of application: If workplace cleaning, sensors or actuators are required

Areas of application: If workplace feeding, armsides or assemblies are required

Use of long gripper fingers possible

Stroke per jaw configurable to the millimeter: from 100 mm to 600 mm

Low weight for weight-optimized handling solutions

Precise handling due to robust hand-touch guidance

Workpiece is clamped axially using a piston-stick principle

Application-specific standard gripper makes up different variants and options and individual configuration

Large stroke in relation to size

Use of long gripper fingers possible

Robust and flexible gripper assembly

Integrated 10-Degrees-of-freedom measuring

Precise gripping due to base jaws guided in rolling bearings

Maximum gripping force up to 610 N with oval piston stroke

S

S:

I

I

520 .. 4620

1850 .. 51650N

13

90 .. 610

30 .. 160

100 .. 110 mm

4.5

1 .. 10

140 .. 2155

19.03 .. 137.7

0.08

0.78 .. 1.12

2.5 .. 15.5

H.25 .. 58.25

0.07

0 .. 3.1

0.11 .. 1.80 / 0.11 .. 2.91

0.00 .. 3.77 / 3 .. 7.7

0.05 / 0.05

0.07 .. 0.08 / 0.07 .. 0.08

800

800

50

125

0.02

0.03

0.02

0.03

41

30

70

80

++

++

+

++

++

+

+

S

S

D

S

D

D

D

D

O

O

O

O

2-finger parallel gripper

Pneumatic grippers

2-finger parallel gripper

Tool

Universal gripper

SFC-plus

Long-jaw grippers

PEA

PSA

SPG



Description

Reliable secure universal gripper according to IP67

Grippers with high torque capacity and long jaw stroke

Gripper with long jaw stroke up to 100 mm and short release round guides

Stable grippers with high maximum capacities and long jaw stroke

For small to medium-sized workplaces

For large workplaces and a wide range of parts

For heavy workplaces and a wide variation in parts

Areas of application: For use in harsh environments such as foundries, grinding shops or stages.

Areas of application: e.g. handling of motor vehicle tires

Applications: for use in harsh environments and with a wide range of workpieces

Areas of application: Assembly, Automotive

Advantages

Precise handling of different workpieces thanks to robust multi-coat guides

Precise handling of different workpieces thanks to robust guidance

Sealed round guidance for long strokes

Precise handling due to robust guidance

Prominently secure sealing thanks to lip seal on the outer circular guides

Use of long gripper fingers possible

Quick clamping thanks to double-piston fast-and-slow function

Universal and flexible gripper assembly

High efficiency due to direct drive assembly

Technical data

Number of jaws	11	6	8	1
Coupling force [N]	310 ... 11250	7200	120 ... 1700	10000
Stroke per jaw [mm]	2 ... 45	150 ... 300	14 ... 100	100
Weight [kg]	0.11 ... 5.7	18.9 ... 33.2	5.77 ... 8.25	15
Recommended workplace weight [kg]	0 ... 40 ... 75	0 ... 14 ... 7	0 ... 8.8	50
Disengaging time [s]	0.03 ... 1.170 ... 1.1	0.7 ... 1.250 ... 1.25	0.12 ... 0.40 ... 0.12 ... 0.3	1,573.5
Max. permissible finger length [mm]	380	900	300	900
Repeat accuracy [mm]	up to 0.01	0.07	up to 0.05	0.1
Process rate [s]	5.7	10	6.2	10
Classification IEC 60068-2-27	5	-	-	-
Sensor system	-	-	-	-
High number of variants	++	+	-	-

Ambient conditions

Clean	●	●	●	●
Temperature/cold/harsh	●	○	●	○
Corrosive/greasy dust and liquids	●	○	●	●
Corrosive/aggressive liquids	○	-	●	●
High temperature range > 90 °C	●	●	●	●
Dust/dirt	●	-	○	○

● = very highly suitable

○ = medium-suited selection

● = highly suitable

++ = wide selection

○ = suitable in customized version

*** = very wide selection

Comparison			
Model	SGC-F	PGF	PGW-series
			
Short gripper for small components with good price-performance ratio	Short universal gripper with good price-performance ratio	Compact universal gripper with surface-guided base jaws	Gripper with high maximum moments and a long jaw stroke
For small to medium-sized workpieces up to 1.95 kg	For light to medium weight workpieces	Suitable for large workpieces	For large workpieces and/or a wide range of parts
Areas of application: Simple applications in small components handling	Areas of application: Mechanical and plant engineering, assembly, handling, automotive	Areas of application: universally applicable	Areas of application: Mechanical and plant engineering, assembly and handling
Cost-effective alternative	Cost-effective alternative	Very good guidance characteristics due to precise tool guidants	The of long gripper fingers provide the of long gripper fingers provide
Wide range of application stories in six sizes	Flexible handling of different workpiece sizes	Minimal interfering clearance despite long stroke	Workpiece is clamped centrally using a plenum-rock principle
Single, functional gripping system all from a single source	Comprehensive sensor accessories and monitoring of the stroke position with appropriate sensor accessories	Universal and flexible gripper assembly	Universal and flexible gripper assembly
8	ID	5	3
16 ... 370	180 ... 8200	190 ... 1900	630 ... 2950
2.5 ... 15	2 ... 35	2.5 ... 11.5	10 ... 103
0.05 ... 0.9%	0.08 ... 17.7	0.1 ... 5.3	2.45 ... 12.8
0 ... 1.85	0 ... 35	0 ... 7.1	0 ... 13
0.03 ... 0.110; 0.02 ... 0.11	0.07 ... 0.70; 0.02 ... 0.7	0.07 ... 0.40; 0.07 ... 0.5	0.3 ... 1.00; 0.3 ... 1.2
60	300	125	250
0.02	up to 0.01	up to 0.02	0.03
20	40	80	41
8	44	8	11
4	*	*	*
6	*	0	0
8	*	*	*
10	*	0	0

3-finger centric gripper

Pneumatic grippers

2-finger centric gripper

Pneumatic	Gripper for small components	Universal gripper	Long stroke gripper
MFT	MFT-plus	MFT-plus	MFT-plus



Description

Small 3-finger centric gripper with base jaws guided on T-slots.	Medium 3-finger centric gripper with high gripping force and high maximum moments.	Universal 3-finger centric gripper with long stroke and high maximum moments.
Especialy suitable for small workplaces.	Flexible handling of a wide range of parts.	For large, sensitive workplaces.
Areas of application: Universally applicable.	Areas of application: can also be used in areas with special requirements such as temperature, chemicals resistance, contamination.	Areas of application: can also be used in areas with special requirements such as temperature, chemical resistance, contamination.

Advantages

Precise gripping with high bearing load capacity thanks to T-slot guidance.	Precise handling due to robust multi-touch grippers.	Sensitive gripping for deformation-free handling.
Monitoring of finger position via position via EPS.	Use of long gripper fingers possible.	Precise handling due to robust multi-touch grippers.
Compact dimensions for minimum interfering contours in handling.	High force transmission and synchronized gripping due to wedge-lock design.	Use of long gripper fingers possible.

Technical data

Number of sizes	6	11	4
Gripping force [N]	20 - 310	255 - 57300	375 - 4200
Stroke per jaw (mm)	1 - 5	7 - 45	20 - 75
Weight [kg]	0.01 - 0.29	0.31 - 80	1.5 - 33
Recommended workplace weight [kg]	0 - 1.15	0 - 22	0 - 22
Dimensioning ratio [1]	0.02 - 0.065; 0.5 - 0.06	0.07 - 1.5; 0.67 - 3	0.15 - 1.05; 0.7 - 0.85
Max. permissible finger length [mm]	45	250	400
Repeat accuracy [mm]	0.03	up to 0.01	up to 0.07
Protection class IP	40	40/64	40
Classification class ISO 14166-1	5	5	5
Sensor options	+	+++	+
High number of variants	+	+++	+

Available accessories

Clamp	●	●	●
Comminuted/crossed gear	○	●	○
Comminuted/wire gear and liquids		○	○
Comminuted/aggressive liquids		○	○
High temperature range > 90 °C		●	○
Desiccant	○		

● = very highly suitable

+ = medium-high suitability

○ = highly suitable

++ = wide selection

○ = suitable in customized version

+++ = very wide selection

Tech	Universal grippers	3D-grip	3F	3C
				
Reliably strong 3-finger centric gripper according to IP67	3-finger centric gripper with high gripping force and high maximum moments and center bore.	Multi-finger gripper for applications in which two or three fingers are insufficient.	Universal 4-finger centric gripper at the compact class with 2-side guidance and best cost-performance ratio.	
For rough or dirty workpieces	Precise handling of a wide range of parts.	E.g. for cylindrical workpieces.	Precise handling of a wide range of parts.	
Areas of application: wide range of applications from wire cells, grinding machines, lathes and milling machines to powder and paint spraying systems.	Areas of application: When workpiece holding, sensors, actuators or customer-side attachments are required.	Areas of application: MedTech, laboratory automation, pharmaceuticals.	Areas of application: Mechanical and plant engineering, assembly and handling, automotive	
Precise handling of different workpieces thanks to robust multi-touch guidance	Precise handling of different workpieces thanks to robust multi-touch guidance	Process-reliable handling despite irregular contours	Cost-effective alternative	
Permanently secure sealing thanks to lip seal on the outer circular profile	Use of long gripper fingers possible	Precise handling due to robust multi-angle guidance	Compact dimensions and low weight for minimum interfering contours in handling	
The of long gripper fingers possible	Multi-functional range of applications due to high gripping forces	High force transmission and synchronized gripping due to wedge-block design	Use of long gripper fingers possible	
5	5	5	7	
230 ... 16500	340 ... 27400	570 ... 6900	325 ... 7190	
2 ... 25	2 ... 25	6 ... 16	2 ... 16	
0.2 ... 20.1	0.26 ... 53	0.3 ... 18	0.12 ... 8	
0 ... 50	0 ... 150	0 ... 34.5	0 ... 10	
0.01 ... 1.80.02 ... 1.8	0.02 ... 2.58.02 ... 2.5	0.02 ... 0.150.02 ... 0.15	0.02 ... 0.30.02 ... 0.8	
100	150	160	200	
up to 0.01	up to 0.01	up to 0.01	up to 0.01	
67	60	40	40	
5				
4	44	44	44	
++	+	+	+	
•	•	•	•	
•	•	•	•	
•	•	•	•	
•	•	•	•	
•	•	•	•	

Angular/radial grippers

Pneumatic grippers

Angular/radial grippers

Pneumatic

Grippers for small components

SME

Radical grippers

PERC-plus

PERC



Description

Narrow double-acting 2-finger angular gripper, narrow 3-finger angular gripper with oval piston and bone drive
Wide radial gripper with powerful 1-pin crank system and oval piston

For small to medium-sized workpieces
Flexible handling of a wide range of parts

Areas of application: Areas which require a stacked, space-optimized gripper arrangement

Areas of application: Can be used in challenging environments

Flexible handling of a wide range of parts

Areas of application: Applications that require a large gripping force with the shortest possible movement sequences at the same time

Advantages

Narrow design, allowing the grippers to be arranged in a row.

Spring-supported gripping force maintenance in the event of a pressure loss

High force transmission and synchronized gripping due to wedge-node design

Variable top jaw design, as grippers are available in jaw version, but also in finger version via intermediate jaws

Equipped with gripping force maintenance in the event of a pressure loss

Optional stroke limitation upon opening, for confined spaces and short cycle times

Highest torsional closing torque at closing angles from -5° to +7° due to kinematics

Optimized cycle time due to innovative damping directly in the drive chain

Higher closing moments for longer and more stable gripper fingers due to maximum power density

Technical data

Number of sizes	8	8	8
Gripping moment (Nm)	0.01 .. 2.8	1.12 .. 10.25	2 .. 295
Opening angle per jaw (°)	15	15	20 .. 90
Weight (kg)	0.0025 .. 0.213	0.13 .. 13.6	0.15 .. 6.72
Recommended workpiece weight (kg)	0 .. 0.45	0 .. 23.23	0 .. 5.95
Closing/opening time (s)	0.015 .. 0.030/0.02 .. 0.06	0.06 .. 0.12/0.04 .. 0.46	0.06 .. 0.71/0.06 .. 0.92
Max. permissible finger length (mm)	62	700	240
Repeatability (mm)	0.05	0.02	Up to 0.05
Protection class IP	30	10	20
Delivery class ISO 14644-1			
Sensor system	+	++	++
High number of variants	+	++	++

Product conditions

Corrosion	●	●	●
Contamination/dust/dirt	○	○	○
Contamination/fat and liquids			
Contamination/oil and liquids			
High-temperature range > 90 °C	●	●	●
UV exposure	○	○	○

● = very highly suitable
+ = medium-sized selection

○ = highly suitable
++ = wide selection

○ = suitable in customized version
++ = very wide selection

* The GAF is an angular parallel gripper, which means the values must be understood as forces [N].

Tech
Grippers for small components

Material gripper

CAT



Compact, double-acting, 2-finger angular parallel gripper for parallel G-D gripping after pivoting in the gripper. Finger up to 90 degrees per jaw.

See our 180° angular grippers for use in contaminated environments.

For small to medium-sized workpieces

Flexible handling of a wide range of parts.

Areas of application: Applications requiring parallel external gripping with previous pivoting of the gripper fingers up to 90° per jaw.

Areas of application: Can be used in dirty environments.

Pneumatically driven angular and parallel movements in a single functional unit.

Completely sealed gripper version.

Maximum positioning accuracy, from to absolute centric clamping in the parallel stroke.

Spring angle adjustable from 20° to 180°.

High force transmission and synchronized gripping due to static kinematics.

Equipped with gripping force compensation in the event of a pressure loss.

Tech
Grippers for small components

CAT



Small, single-acting, press-fit 2-finger angular gripper with spring return.

Small, single-acting, press-fit 3-finger angular gripper with spring return.

For small to medium-sized workpieces.

For small to medium-sized workpieces.

Areas of application: Applications requiring corrosion resistance and anti-static properties.

Areas of application: Applications requiring corrosion resistance and anti-static properties.

Cost-effective alternative.

Cost-effective alternative.

Light and corrosion free, as housing is made from fiberglas-reinforced plastic.

Light and corrosion free, as housing is made from plastic.

High power transmission and synchronized gripping thanks to single-acting double-piston drive with lever transmission.

High power transmission and synchronized gripping thanks to single-acting 3-piston drive with lever transmission.

	1	5	3	3
92 ... 430°	8.2 ... 34.7	0.8 ... 4.95	1.15 ... 7.45	
10 ... 90	10 ... 90	3	3	
0.3 ... 1.73	0.5 ... 4.46	0.04 ... 0.06	0.05 ... 0.17	
0 ... 1.25	0 ... 7.2	0 ... 2.8	0 ... 1.2	
0.05 ... 0.25 / 0.05 ... 0.35	0.4 ... 0.3 / 0.5 ... 0.6	0.06 ... 0.08 / 0.04 ... 0.05	0.07 ... 0.09 / 0.03 ... 0.05	
65	125	50	50	
0.05	0.1	0.1	0.1	
40	67	20	20	

	4	4	4	4
●	●	●	●	●
○	○	○	○	○
●	●	●	●	●
○	○	○	○	○

Special grippers

Pneumatic grippers

Special grippers

Tech

Gripping grippers

GNC

Grippers with compensation unit

GNC-S

GNC-S with ACE



Description

3-finger gripper for process-related incremental and external assembly of O-rings

For O-rings, quad-rings, etc. up to 160 mm outer diameter

Areas of application: Automated assembly

Universal gripper

Flexible handling of a wide range of parts

Areas of application: Fully automated loading and unloading of machining centers

Universal gripper with compensation unit

Flexible handling of a wide range of parts

Areas of application: Fully automated loading and unloading of clamping devices such as vices

Advantages

External and internal assembly with one gripper for flexibility and cost savings

Reliable performance due to new mounting principle for high availability

Standard assembly finger for external assembly for common ring sizes for tool change without the use of rotators or gauges

Cost effective module consisting of a universal gripper PGH-plus/PZK-plus and a shank interface

Fast, automated gripper change from the tool rack

Cost effective module consisting of a universal gripper PGH-plus/PZK-plus and a shank interface

Fast, automated gripper change from the tool rack

Fully automatic tool change without the use of rotators or gauges

Sensor system

+

+

+

High number of variants

+

+

+

Ambient conditions

Dust

●

●

●

Contaminated/dirty dust

●

●

Contaminated/dirty dust and liquids

●

●

Contaminated/aggressive liquids

●

●

High-temperature range > 90 °C

●

●

Chemicals

○

● = very highly suitable
+ = medium-sized selection

● = highly suitable
+ = wide selection

○ = suitable (in compensated version)
++ = very wide selection

G200-T

G200-M

EGS

Universal hole gripper
100



Vacuum gripper G200-T for spin-on interfaces

For flat workpieces weighing up to 4.9 kg



Magnetic gripper for spin-on interfaces

For flat, ferromagnetic workpieces



Cleaning unit for up to 30 bar operating pressure

For machine fluid filtered, max. particle size of 20 µm or filtered compressed air in accordance with ISO 8573-1:2010 (7.5x)



Light gripper made of very flexible polyamide with closed diaphragm system

For light workpieces up to 3 kg weight such as small components, plastic components and sand cores

Areas of application: For fully automated loading and unloading

Areas of application: For fully automated loading and unloading

Areas of application: For cleaning of clamping devices and for automated cleaning of attribute tools

Areas of application: Particularly suitable for highly dynamic applications with lightweight workpieces

Cost-effective unit for flexible automation in the machine

No electricity required, cleaned using cooling lubricant

Cost-effective unit for flexible automation in the machine

High dynamics in the application due to low weight

Fast, automated gripper change from the tool rack

Cost-effective unit for flexible automation in the machine

Fast, automated cleaning for maximum machine utilization

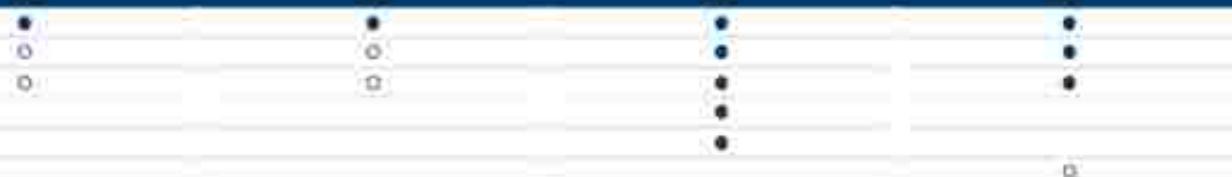
A robust membrane system and internal stop prevent the explosion membrane from damage

Fully automatic tool change without the use of robots or gantries

Fully automatic tool change without the use of robots or gantries

Increased safety for machine operators

A long service life ensures long-lasting economical use

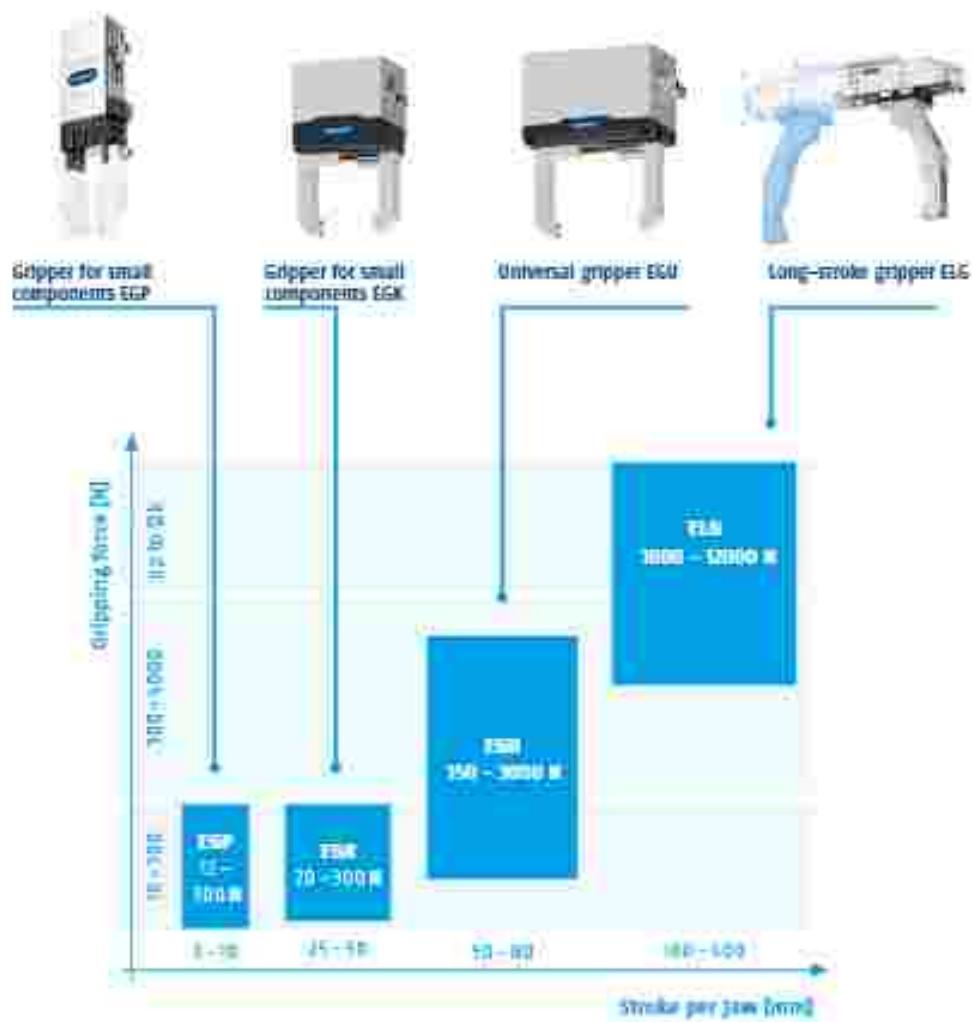


Mechatronic grippers

Our range of electric parallel grippers currently comprises four product series that are optimally adapted for use in various application areas in terms of gripping force and stroke. This allows you to quickly find the right gripping solution for your application.

For the requirements of modern process flows, mechatronic gripper solutions offer many advantages

- **Flexibility:** Variety of parts, adjustment options (positioning, stroke, force, modes), future-proof thanks to new software functions that can be added at a later date
- **Connectivity:** Added value through standardized interfaces (flexible and simple networking with all relevant cobot and controller manufacturers)
- **Process feedback:** For greater process stability and reliability due to integrated monitoring and analysis options
- **Independent of compressed air:** For improved availability, cleanliness and sustainability even in mobile applications



Connectivity EGK and EGU

EtherCAT

Modbus
RTU



PROFINET

IO-Link

EtherNet/IP



Communication interfaces

For easy integration, the two new mechatronic grippers EGU and EGK are equipped with a variety of communication interfaces.

This allows them to be quickly and easily connected with all relevant robot and controller manufacturers.

PLC Integration

For a seamless interaction between gripper and PLC control, function modules for the programming interface of leading manufacturers are available (Allen Bradley, Beckhoff, Siemens). This means that all gripper functions can be used directly without any additional programming effort.

Robot Integration

In order to be able to integrate grippers quickly and easily into robot control systems (ABB, FANUC, KUKA, YASKAWA), software modules are available. These enable the use of all gripper functions without additional programming effort.

Application examples



Automated machine loading



Assembly and joining tasks



Handling of printed circuit boards



Handling of samples

2-finger-parallel grippers

Electric grippers

2-finger parallel grippers Gripper for small components

Universal gripper



Description

2-finger gripper for small components with smooth-running base jaws guided on roller bearings.

For precise small components handling with short cycle times.

Areas of application: Electronics manufacturing, laboratory automation and assembly automation in rigidly automated production processes.

Flexible 2-finger gripper for small components for maximum workpiece variety with maximum process reliability.

For delicate and fragile workpieces such as printed circuit boards, samples and trays.

Areas of application: Flexible production processes in electronics manufacturing and laboratory automation.

Flexible 2-finger universal gripper for the highest level of workpiece variety with maximum robustness.

Universal workpiece handling, even for large and heavy workpieces.

Areas of application: Loading and unloading of machine tools, assembly and joining tasks with externally acting process forces; flexible picking and palletizing in logistics.

Advantages

Compact dimensions for minimum interfering consumers in handling.

Versatile and productive due to the long and freely programmable jaw stroke with seamless gripping force adjustment.

Control via digital IO for easy commissioning and rapid integration into existing systems.

Gripping force maintenance with less friction.

Gripping force maintenance with less friction.

Control via IO-Link. Enables pre-positioning of the gripper fingers and evaluation of the gripper position as well as the adjustability of specific gripping modes.

Always referenced in the event of both emergency stop and power failure thanks to integrated absolute encoder.

Always referenced in the event of both emergency stop and power failure thanks to integrated absolute encoder.

Technical data

Number of jaws	2	3	4
Gripping force [N]	12 .. 200	20 .. 300	150 .. 1000
Stroke per jaw [mm]	1 .. 10	16.5 .. 51.5	41 .. 80
Dead weight [kg]	0.11 .. 0.81	0.18 .. 1.81	1.34 .. 7.88
Max. permissible finger length [mm]	80	130	200
Nominal voltage [V]	24	24	24
Protection class IP	30	67	67
Communication interface	Digital IO, IO-Link	PROFINET, EtherCAT, EtherCAT, IO-Link, Modbus RTU	PROFINET, EtherCAT, EtherCAT, IO-Link, Modbus RTU
Sensor system			
Joint number of variants	444	444	444

Additional characteristics

Class	*	*	*	*
Corrosion-resistant jaws				
Communication-free jaws and grippers				
Communication/aggressive liquids				
High-temperature range > 10 °C				
Cleanroom	*	*	*	*

* = very highly suitable
** = medium-sized selection

* = highly suitable
** = wide selection

CI = suitable in customized version
*** = very wide selection

Long-stroke gripper
ESG

Long-stroke 2-finger long-stroke gripper with a gripping force of up to 1000 N.

For large, bulky and heavy workplaces.

Applications: customized, handling of crates, boxes, films, white goods and much more.

Collaborating
Grippers ESG-C

Collaborating 2-finger gripper for small components with current up to 24 V and weight up to 10 g.

For small and light workpieces.

Areas of application: Applications with direct collaboration between humans and robots.

Cylindrical gripper
EN

2-finger parallel gripper with high maximum moments due to multi-tooth guidance.

For cylindrical workplaces.

Areas of application: loading and unloading of machine tools.

Special grippers

Servo-electric 5-finger gripping hand SWH



The servo-electric 5-finger hand grips almost as perfectly as the human hand.

For a wide variety of gripping and manipulation tasks.

Areas of application: mobile robotics, research and development.

Dimensions

1100 ... 1700

100 ... 600

8.1 ... 58.3

800

Motor-independent:

20 ... 40

Comments - appendices:

Dimensions

145 ... 736

0 ... 10

0.59 ... 1.18

80

76

30

Stainless steel

Dimensions

500 ... 900

8 ... 10

0.88 ... 2.48

80

76

41 ... 65

mm/unit

Dimensions

Various gripping operations can be executed with high sensitivity thanks to the moving parts with a total of nine degrees of freedom.

Reliable grip on objects due to smooth gripping surfaces.

Extremely compact design due to integration of the complete control, regulator, and power electronics in series.



ADHESO Adhesive gripper



The ADHESO gripper technology is based on an adhesive system inspired by nature. The adhesive forces used by animals such as geckos for locomotion are now being utilized by SCHUNK for use in handling applications in the most diverse of fields.

The advantages of the ADHESO gripper technology are revolutionary

- **Low operating costs** due to energy-efficient gripping without an additional energy supply
- **Gripping without any visible residues** for sensitive workpieces
- **No particle emission**, making it suitable for clean room applications
- **Versatile in use and ideally adapted** to different ranges of applications

Material and surface

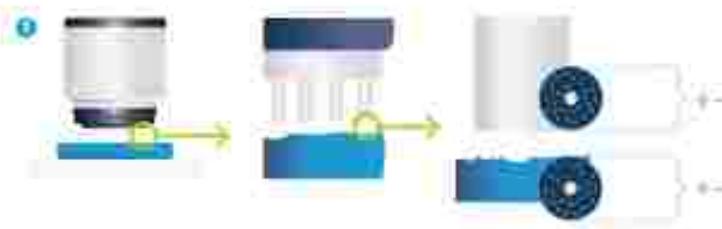
SCHUNK grippers with ADHESO gripper technology have a distinctive surface architecture made of special polymers. The result is a structure of extremely finely structured legs, which adheres residue-free to the different materials and objects. The scalability options and use of different material characteristics allows the adhesive structure to be adapted to different workpieces and surfaces. This makes grippers with ADHESO technology easy to customize for the most diverse workpieces and applications.



The German Federal Ministry for Economic Affairs and Climate Protection awarded the innovative ADHESO gripper technology from SCHUNK with the IKU 2022.

Principle of function

The bionic-inspired ADHESO gripper technology is based on the principle of adhesion, using intermolecular acting Van der Waals forces for handling various workpieces and materials. Due to the high variability of the adhesive structures, grippers with ADHESO technology can be individually tailored to different applications.



- Initial粘附 (Initial adhesion)
- Stripping process



Application examples



Handling of lab samples



Handling of semiconductors



Handling of vehicle components



Handling of food

Magnetic gripper

As if by superpower, SCHUNK's magnetic grippers move ferromagnetic components in any position and size. Whatever their position – the workpieces are always gripped quickly and securely. A short pulse of current is all it takes to get the magnetic grippers ready for use. Uncomplicated, easy to handle and exceptionally strong – it's time to add the invisible force of magnetism to your production!

The advantages of magnetic gripping technology offer you real added value

- **High holding forces for reliable part handling** in compact systems
- **Actuation via 24 V voltage supply** saves energy and simplifies connection and wiring
- **Workpiece accessibility from five sides** free from interfering contours
- **Low weight for high dynamics** in challenging applications
- **Reliable maintenance of holding force** for process-reliable use even in emergency-stop scenarios

Application examples



Handling of battery round cells



Handling of sheet metal



Bin picking of raw parts



Handling of mirrors

Electromagnetic grippers

EN

DE

**Description**

Compact electric-permanent magnetic gripper for energy-efficient handling

Compact electric-permanent magnetic gripper for energy-efficient handling with integrated electronics and feedback function

For ferromagnetic workpieces weighing up to 110 kg

For ferromagnetic workpieces weighing up to 20 kg

Areas of application: Universally applicable for a wide variety of parts

Areas of application: Universally applicable for a wide variety of parts

Advantages

Reliable part handling in compact systems due to high holding forces in very small spaces

Reliable part handling in compact systems due to high holding forces in very small spaces

Low weight for high dynamics in challenging applications

Compact design due to integrated electronics without additional controllers

Reliable gripping force maintenance for process-reliable use even in emergency-stop scenarios

gt; 1 ratio of workpiece weight to dead weight for high dynamics in demanding applications

Technical data

Number of sizes	16	8
Shipping range (R)	100 ... 30370	530 ... 10550
Weight (kg)	1 ... 25	1 ... 8
Recommended workpiece weight (kg)	0 ... 110	0 ... 20
Closing/opening time (t)	0.3	0.2
Nominal voltage (V)	400 AC	24 DC
Nominal current (A)	2.2 ... 12.8	1.1 ... 9.8
Protection class (IP)	54	57
Communication interface	Universally dependent	Digital IO
Min. number of variants	***	**

Motor & control

Motor		
Controller	External	Integrated
Controller type	ECU	

Medium conditions

Dust	●	●
Concentrated dust	●	●
Unconcentrated dust and liquids	○	○
Corrosive/aggressive liquids		
High temperature range > 60 °C		
Desertion:	○	○

● = very highly suitable

○ = medium-suited selection

○ = highly suitable

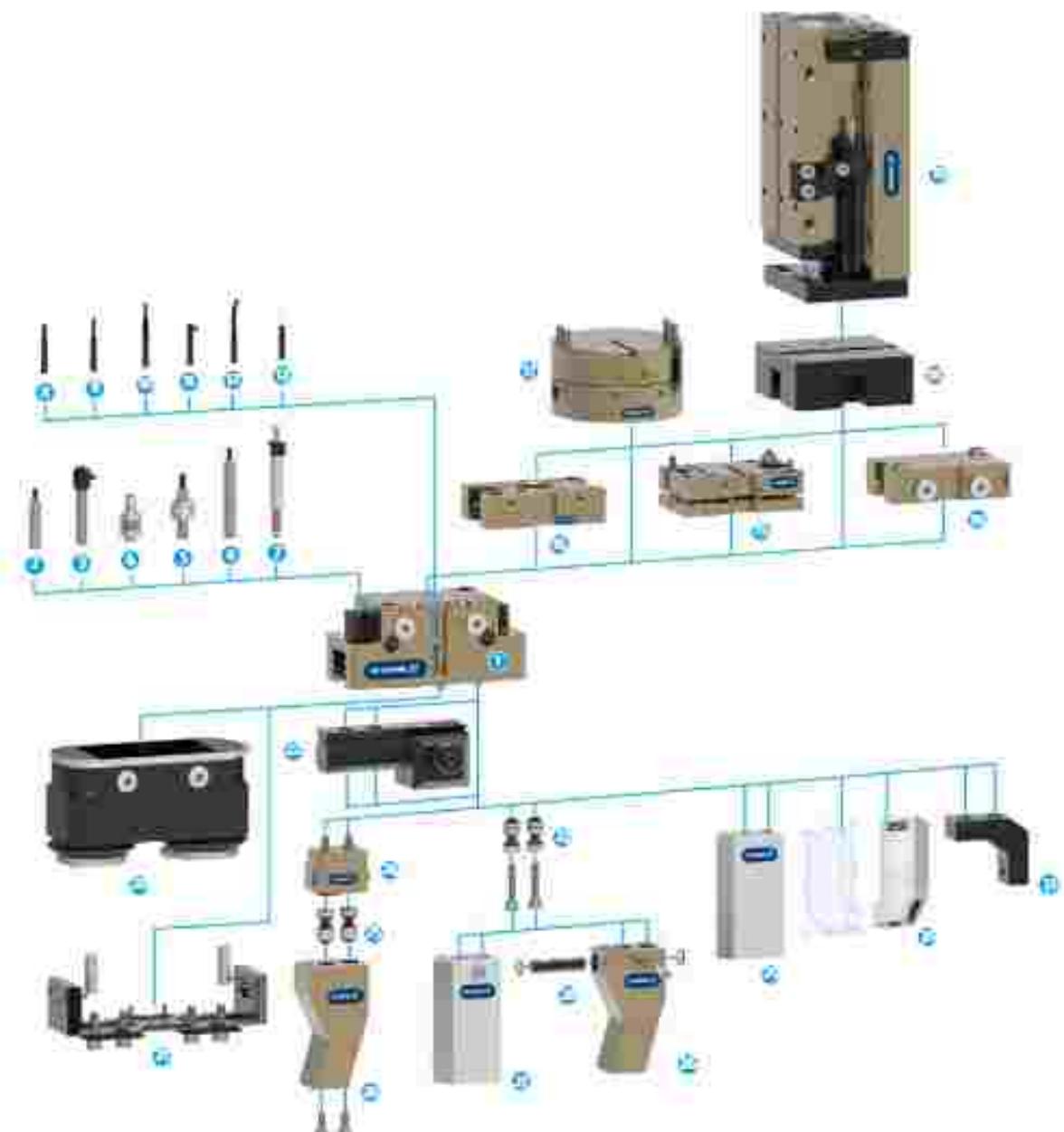
*** = wide selection

○ = suitable in customized version

*** = very wide selection

Accessories

SCHUNK also offers suitable accessories for the extensive gripper range. The universal gripper PGN-plus-P, for example, features a large number of variants and a superior range of accessories offering everything needed for flexible use in your specific automation application. For each kind of application and handling requirement – and also under extreme conditions.



- FOX-plus-7**
Universal 2-finger parallel gripper with a high gripping force and high throughput capacities due to the use of a multi-finger guidance

Sensor system

- IN**
Inductive proximity switch with mounted cable and straight cable outlet
- IN-1-3A**
Inductive proximity switch with mounted cable and lateral cable outlet
- IN-C-08**
Inductive proximity switch, circuit program
- FPS**
Flexible position sensor for monitoring up to five different, freely selectable positions
- APS-Z30**
Inductive position sensor for precise position detection of the gripper jaws with analog output
- APS-M15**
Mechanical measuring system for accurate acquisition of the gripper jaw position with analog output
- MMS 22**
Magnetic switch with straight cable outlet for monitoring a position
- MMS 22-210**
Magnetic switch with straight cable outlet for monitoring a freely programmable position
- MMS 22-212**
Magnetic switch with straight cable outlet for monitoring two freely programmable positions
- MMS 22-P11-HD**
MMS 22-P11 in robust design
- MMS 22-P12-HD**
MMS 22-P12 in robust design
- MMS 22-5A**
Magnetic switch with lateral cable outlet for monitoring a position
- MMS 22-P11-SA**
Magnetic switch with side cable outlet for monitoring a freely programmable position
- MMS-2**
Magnetic switch with straight cable outlet for monitoring two freely programmable positions
- MMS-6**
Analog magnetic switch with straight cable outlet for measuring the gripper jaw position with analog output and teach function
- MMS-ED**
Magnetic switch with straight cable outlet for measuring the gripper jaw position with IO-E interface and teach function

Complementary Products

- CWS**
Manual change system with integrated air feed-through for simple exchange of the handling components

- TOL**
Tolerance compensation unit for compensation of small tolerances in the plate
- SIV-P-I-T**
Pressure maintenance valve for temporary force and position maintenance
- AGE**
Compensation unit for compensation of large tolerances along the X and Y axes
- ASG**
Adapter plate for combining various automation components in the modular system
- LIM**
Linear module with pneumatic drive and step-free pre-tensioned junction rollers
- HDE**
Sleeve for protection against dirt
- SAB**
Bumper version, restraint kit

Finger Accessories

- BZB**
The universal intermediate jaw allows for the fast tool-free and reliable plugging and shifting of top jaws to the gripper
- BSWS-AR**
Adapter coupling of jaw quick-change system for fast, manual change of top jaws
- BSWS-B**
Locking mechanism of the jaw quick-change system for fast, manual change of top jaws
- BSWS-A**
Adapter coupling of the jaw quick-change system for adaptation to the customized finger
- Customized fingers**
- BSWS-KBB**
Finger blank made of aluminum with interface to the jaw quick-change system
- BSWS-SBH**
Finger blank made of steel with interface to the jaw quick-change system
- BSWS-RW**
Locking mechanism for the integration of the jaw quick-change system into customized fingers
- SAURAN**
Finger blanks made of steel or aluminum with standard screw connection diagram
- FGF**
Configurable, workpiece-specific gripper finger made of aluminum or steel
- ZBA**
Intermediate jaws for protection of the mounting surface

Finger accessories		Workpiece-specific gripper fingers	Top jaws blank	Jaw quick-change system	Jaw quick-change system
		Regens	Regens	RSNC-M-A	RSNC-M
					
Workpiece-specific, configurable gripper finger made of aluminum or steel	Blanks made of aluminum or steel for work by the customer	Jaw quick-change system consisting of a base and two adapter pins	Jaw quick-change system consisting of a base and two adapter pins		
Suitable for many gripper types	Suitable for various gripper types	Handling of various workpieces	Handling of various workpieces		
Areas of application: Universally applicable	Areas of application: For quick and easy creation of top jaws by adding the clamping contours	Areas of application: With highly diverse workpieces for quick jaw changes with any clamping contours	Areas of application: With highly diverse workpieces for quick jaw changes with any clamping contours		
Easy configuration of individual gripper fingers	for jaw blanks with jaw quick-change systems, there are no more interesting mounting times for the finger contours	Fast replacement of the gripper fingers thanks to the form-fit locking mechanics	The gripper can be used universally in various applications		
Short delivery times for quick availability without tying up your own resources	Easy to assemble due to standardized drilling pattern	Saving time when converting applications	Tool-free jaw change via the unlocking button		
No CAD program or expertise required thanks to intuitive web tool	High replacement accuracy due to centering	Firm up to the maximum loadability of the base jaws	Saving time when converting applications		

Jaw quick-change system with top jaw blank	Jaw quick-change system	Adjustable intermediate jaw	Complementary products	Protective cover
ARTICLE-NR.: 8000-0000-0000	ARTICLE-NR.: 8000-000-000	ARTICLE-NR.: 8000-000-000	ARTICLE-NR.: 8000-000-000	ARTICLE-NR.: 8000-000-000
				
Fast replacement of the gripper fingers thanks to the form-in-clamping mechanics	Fast replacement of the gripper fingers thanks to the form-in-clamping mechanics	Universal intermediate jaw for fast tool-free and reliable plugging and shifting of top jaws on the gripper	Prevents bursting of the module in the event of a loss in air pressure in the supply line.	Protective cover for gripper against external influences in a dirty environment
Handling of various workpieces	Handling of various workpieces	Handling of various workpieces	This is especially useful for gripped where a mechanical grip force maintenance option is not possible	Suitable for grippers PGK-plus, PGH-plus, PDK-plus, ESK and EKH
Areas of application: With highly diverse workpieces for quick jaw changes with any clamping contours	Areas of application: With highly diverse workpieces for quick jaw changes with any clamping contours	Areas of application: With highly diverse workpieces that can be covered by increasing the clamping width	Areas of application: Temporary take or position maintenance for various permanent assemblies	Areas of application: Suitable for applications up to IP65. If additional sealing of the cover housing is provided
Saving time when converting applications	Saving time when converting applications	Gripper and finger-safe centering for universal and flexible assembly of the gripper	Greater operational safety when using pneumatic components	Cost-effective for economical handling
Fit up to the maximum readability of the base jaws	Fit up to the maximum readability of the base jaws	Flexible guide strip; suitable for long gripper fingers	Long-term reliable application can be guaranteed thanks to robust design	
		Precise and repeatable grid	Universally applicable, as it can be combined with almost any pneumatic actuator	Space-saving due to low mounting contours

Sensors

Sensors		Monitoring of one position 1 digital switching points		Monitoring of several positions 2 digital switching points	
		MHS-22	MHS-PI 1	MHS	MHS-PI 2
					
Technical data					
Number of sites	1	1	10	2	1
Operating principle	Magnetic	Magnetic	Inductive	Reed	Magnetic
Max. IP protection	67	67	67	67	67
Supply voltage (V DC)	24	24	24	24	24
Max. current on contact (mA)	50	50	100 ... 200	600	25
PNP version	●	●	●	●	●
NPN version	●	●	●	●	●
LED display	●	●	●	●	●
Min. temp., ambient temperature (°C)	-10 ... 70	-10 ... 70	-25 ... 70	-5 ... 70	-10 ... 70
Dust	●	●	●	●	●
Spatter			●		
Connection type					
Number of axes	3	3	3	3	4
Cable version	●	●	●	●	●
Connector M8 version	●	●	●	●	●
Connector M12 version			●	●	
Mounting instructions					
Clash	●	●	●	●	●
Easy commissioning	●	●	●	●	●
Extremely short	●		●	●	

• **Army and military support**

Cables

Cables	Sensor cable	Accessories
		
Description	Optimally suited for digital transmission of SCHUNK sensor technology	Perfectly suited to supply and control SCHUNK components
	Area of application: For use on all SCHUNK encoders as well as components with integrated sensor technology.	Area of application: The connectors are used for every gripper, rotary and linear module, and also for numerous components in the robot accessories line.
Advantages	industrial standard plug connector different connections possible (straight/angled)	industrial standard plug connector different connections possible (straight/angled)
	Combination with plug-in connector possible	Combination with plug-in connector possible

Monitoring of the overall stroke					
5 digital switching points		IO-Link signal		Analog signal	
MHS-P	MPS	MHS 2x IO-Link	MPS-MI	MPS-200	MHS-A
1	2	1	1	1	1
Magnets	Magnets	Magnets	Mechanical	Mechanical	Magnets
67	67	67	67	67	57
24	24	24	24	24	24
100	200	25	-	-	-
•	•	•	•	•	•
5...55	-25...70	5...55	0...50	-10...70	-5...55
•	•	•	•	•	•
4	7	3	4	3	3
•	•	•	•	•	•
•	•	•	•	•	•
•	•	•	•	•	•

Communication cable	Power/signal cable	Plug connector

Optimally suited for reliable transmission of bin signals from the higher-level control system to the mechatronic SCHUNK components.

Areas of application: The connectors are used for every sensor, gripping, rotary and linear module, and also for numerous components in the other accessories field.

Perfectly suited to supply all SCHUNK components.

Areas of application: The connectors are used for every sensor, gripping, rotary and linear module, and also for numerous components in the other accessories field.

For the assembly of cables for sensors and between

components, actuators and cables. Wherever customized cable lengths are required.

Industrial standard plug connector

Industrial standard plug connector

Industrial standard plug connector

Different connections possible (straight/tangled)

Different connections possible (straight/tangled)

Different connections possible (straight/tangled)

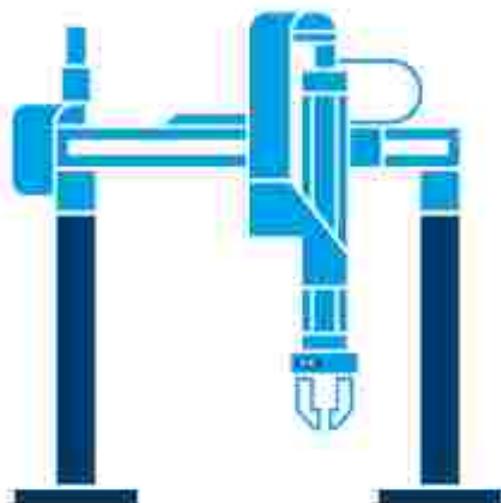
Available in width or cable stack capability

Suitable for connection to the respective SCHUNK component

Easy assembly

Automation with SCHUNK: We can help you to master any challenge

SCHUNK offers the world's most comprehensive product portfolio for technical solutions for automated handling of workpieces. Whether pick & place units, linear modules or multi-axis systems – as a complete supplier of handling solutions, we will be happy to advise you. Application-specific automation systems provide high dynamics during short cycle times – from small parts assembly in the production of electronics to the loading and unloading of machine tools, to the handling of food products, pharmaceuticals or medical devices.



Swivel units

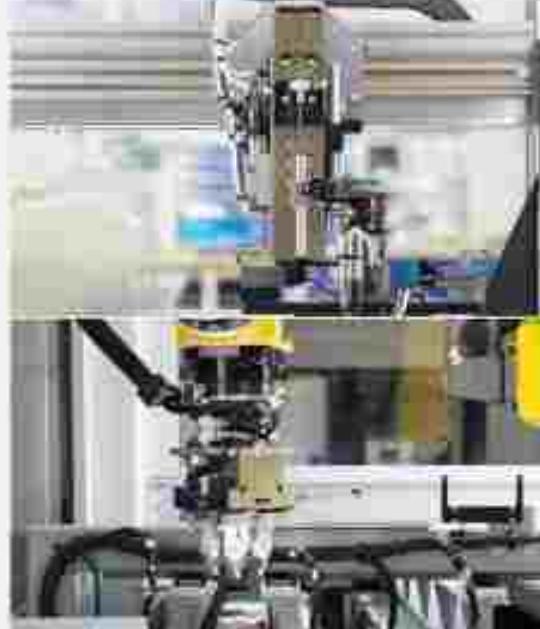
SCHUNK offers a unique range of swivel and rotary modules with various options.



Swivel units

Linear modules & axis systems

Whether it's a variety of linear technology from a single source for high-speed assembly automation or an extensive portfolio for machine tooling and unloading – SCHUNK is your partner for every type of handling process automation.



Linear modules & axis systems

Change systems & feed-through modules

In the field of automation, SCHUNK offers the most comprehensive portfolio of components for robot applications from small components to heavy load handling.



Change systems & feed-through modules

Rotary feed-throughs

SCHUNK rotary feed-throughs are the modern standard for economy use and for automation.



Compensation units & collision protection

Compensation units & collision protection

To prevent damage to tools or workpieces, SCHUNK compensation units ensure the necessary flexibility. Moreover, monitoring modules are an effective tool for process-reliable manufacturing in automated handling processes.



Force/torque sensors

Force/torque sensors

Smart process results are needed, intelligent performance sensors are the smart and precise option with the required sensitivity.



Machining tools

Machining tools

Boring, grooving and parting – machining tasks such as removing material or finishing workpieces can be completed quickly and easily with the help of the H-TECHNO tools.

Automation technology

Pneumatic swivel units

Swiveling and rotating are universal processes required in any industrial situation comprising automated handling of workpieces. The requirements for the components used are very high and also very specific. SCHUNK offers a unique range of swivel and rotary modules with various options.

Pneumatic swivel units from SCHUNK offer you many advantages:

- **The right product for your application**
available as standards thanks to a diverse range of series
- **Numerous options available**
e.g. integrated media and electrical feed-through and pneumatic center position
- **Specialty developed shock absorbers**
for high mass inertias and fast cycle times
- **online configurator for gripper-swivel units**
makes it easier to find the right product
- **Wide range of accessories available**

Application examples



Handling of raw and finished parts



Sheet metal handling

Electric swivel units



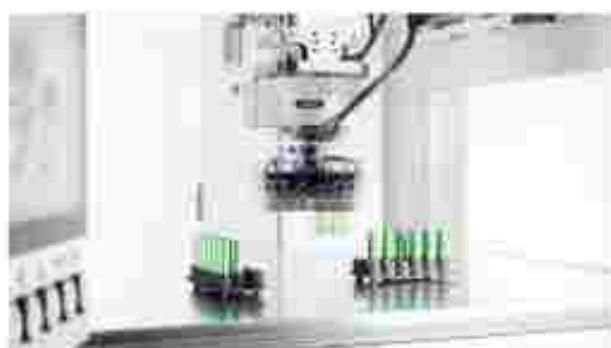
The electric swivel units from SCHUNK more than meet the high requirements for swivel and rotary movements in automation. In addition to the diverse options and the wide range of variants, the universal use of the swivel and rotary modules are perfect for custom applications of any kind.

Electric swivel units

from SCHUNK offer you many advantages:

- **The right product for your application**
Available as standard thanks to series diversity
- **The possibility of any intermediate position enables great process versatility**
and optimal adaptation to the relevant application
- **Extensive consulting service**
ranging from choosing the appropriate technology to design tasks
- **Various actuation options**
facilitate easy integration into existing control concepts
- **Numerous options available,**
e.g. integrated media and electrical feed-through and integrated holding brake

Application examples



Handling of battery round cells



Handling of electronic components



Handling of finished products

Pneumatic rotary modules

Swivel units

	Swivel units	Swivel head	Value swivel units
	S8H	S8H-plus	S8H-plus
Description	<p>Universal swivel unit for rotating and swiveling movements.</p> <p>Usable with any swiveling movements.</p>	<p>Universal swivel units for rotating and swiveling movements.</p> <p>Usable with any swiveling movements.</p>	<p>Universal swivel head for simultaneous loading and unloading of workpiece with integrated fluid and electrical feed-throughs.</p> <p>Recommended for loading and unloading machine tools.</p> <p>Hand-functional range of applications.</p>
Advantages	<p>Heavy graded series with a steady increase in torque.</p> <p>Large central bore for feed-through of cables and hoses with the same unit height.</p> <p>Pre-adjusted shock absorber sensor for simple and fast start-up.</p>	<p>Heavy graded series with a steady increase in torque.</p> <p>Swivel angle 90° or 180° selectable; application-specific angles are available on request.</p> <p>Choice of end position offsetting: +2°/-2° (small) or +3°/-9° (large).</p>	<p>Right electrical signals can be fed through without cables.</p> <p>Significant minimization of wear and shorter loading times due to high damping power thanks to hydraulic shock absorbers.</p> <p>Media feed-through and drive connection via screw connection or tube-free direct connection possible.</p>
Technical data			
Angle of rotation < 162° [°]	0...180	0...180	0...180
Angle of rotation > 162° [°]			
Number of sizes	8	8	7
Torque (Nm)	0.05...22.7	3...115	3...59.9
Front weight (kg)	0.252...9.76	1.3...26.5	2.3...21.7
Max. permissible mass moment of inertia (kgm²)	0.0007	37	7.5
Repeatability accuracy [°]	0.03...0.06	0.05	0.05
Protective class IP	60/65	67	67
Gripping force (N)			
Starter per hour (min)			
Recommended working weight (kg)			
Deceleration time (s)			
Max. permissible finger length (mm)			
Options/Options			
Linear bore	●		●
Hydraulic rotary feed-through	●	●	●
Electric rotary feed-through	●	●	●
Linear position	●	●	●
ATEX certified		●	●
Rotating force measurement device			
Standard = Options			
Infrared proximity switch	●	●	●
Magnetic switch	●	●	●
Additional conditions			
Class	●	●	●
Electrical consumption:	●	●	●
Delivery time:	●	●	●

● = Fully supported

Rotary indexing table Swivel finger Gripper swivel module with gripper

GM-10

GS1-0

GFS

GS4-7



Universal swivel unit with high torque up to 22 Nm for fast swivel tests.

Ring indexing unit for endless turning with a rotation angle up to 90° per cycle.

Swivel finger for turning workpieces that are held by a gripper, for example, or it can also be used as a special swivel unit.

Compact rotary gripping combination consisting of a powerful motor drive, an end-position and damping device and a 3-finger parallel gripper.

For fast movement cycles

Multi-functional range of applications

For gripping and swiveling small to medium-sized workpieces in clean environments.

Step system with integrated fine adjustment of the swivel angle for sensitive adjustments of the end positions.

Right, left, or alternating operation are possible.

Integrated hydraulic end position dampers for rapid swiveling cycles.

Space-saving since the rotary drive, end-position damping unit and gripper are merged in one compact module.

Highest repeat accuracy due to direct drive or the rotary table with integrated linear cylinders.

Maximum damping power due to the use of hydraulic shock absorbers when using large rotary tables.

No positions lost from play for maximum positioning accuracy.

Cost-saving since adapter plates are not needed and also due to the reduction in project planning and engineering design costs.

Extremely compact design for minimal interfering contours.

Large center part for simple attachment of further components.

Unit without drive and damping as a cost-effective version of the standard bearing position.

Powerful for even greater masses and inertias due to the variant with hydraulic shock absorbers.

GM-100

GS1-100

GS-100

with cycle 22.5° ... 90°

6

2

6

6

0.3 ... 32

3.1 ... 29.3

0.04 ... 10

0.3 ... 2.5

0.65 ... 8.3

1.3 ... 3

0.55 ... 5

0.37 ... 1.51

0.77

0.6

up to 0.025

0.04 ... 0.09°

0.07

0.02

40

50

56

30

39 ... 162

1.5 ... 10

0.2 ... 0.81

0.01 ... 0.05 / 0.01 ... 0.05

55

100

100

100

100

150

150

150

150

200

200

200

200

250

250

250

250

300

300

300

300

350

350

350

350

400

400

400

400

450

450

450

450

500

500

500

500

600

600

600

600

700

700

700

700

800

800

800

800

900

900

900

900

1000

1000

1000

1000

Electric rotary modules

Swivel units

Swivel units			
	EN	FR	ES
Description	Electric, heavy-duty rotary module with adaptable servomotor, rotary angle > 360°, center bore, and optional feed-throughs.	Servo-electric integrated rotary unit with angle of rotation > 360°, center bore, and precision gear.	Modular rotary units with powerful torque motor with absolute encoder, transducer and electric and pneumatic rotary feed-through.
Advantages	Modular drive concept for adaptation of all common servomotors like Bosch and Siemens.	Brushless DC servomotor for flexible use by controlled position, velocity, and torque.	Absolute-path measuring system for less programming effort and time saving when commissioning and in operation.
	Easy system integration through use of a preprogrammed motor and already established times bus and safety technology.	High torque, velocity, and precision for rapid acceleration and short cycle times with high precision.	High dynamics for shorter cycle times resulting in high productivity.
	Drive can be mounted 180° for optimum adaptation to ports or corners.	Complete integration of the entire control, regulating and power electronics for setting up a decentralized control system.	Integrated air and electric feed-through for reliable electricity, gas and water supply of the grippers.
Technical data			
Number of sites	3	2	7
Torque (Nm)	75	0.75 .. 6.0	0.4 .. 1.2
Max. speed (RPM)	62.5	35 .. 137	600
Feed weight (kg)	15.5	0.75 .. 1.55	1.2 .. 1.8
Max. permissible mass moment of inertia (kgm²)	20	0.3	0.011
Repos accuracy (°)	0.075	0.00%	0.01
Gear ratio	48	32 .. 100	
Intermediate circuit/universal voltage (V)	Model-dependent	24	500
Nominal current (A)		1.7 .. 5.5	0.43 .. 1.6
Diameter of center bore (mm)	22		
Number of electric feed-throughs	0	0	4
Number of pneumatic feed-throughs	0	0	2
Protection class IP	IP5	54 .. 65	60 .. 54
Type of measuring system	Model-dependent	Incremental	Absolute measuring system HOPPSEN and SINE-CIQ
Angle of rotation (°)	> 360°	> 360°	> 360°
Gripping force (at gripping angle 90°)			
Semi-gripping angle per jaw (max 30°)			
Recommended gripping weight (kg)			
Closing / opening time (s)			
Max. permissible finger length (mm)			
Mount & connection			
Mount	Adhesive	Infrared	Integrated
Commuter	Terminal	Integrated	External
Unidirectional type	Model-dependent		Bosch Rexroth, Siemens*
Optimizations			
Series bore	●	●	
Pneumatic rotary feed-through	●		●
Electric rotary feed-through			●
Brake	●		
Additional functions			
Drift	●	●	●
Energy consumption	●	●	●
Emergency stop	●	●	●

● = highly recommended supported

* = additional commuters available upon request

Gripper swivel module with parallel gripper



Electric universal rotary unit with torque motor and angle of rotation > 360° as well as optional holding brake, rotary feed-through and IP54

Electric universal rotary unit with torque motor and angle of rotation > 360°, protection class IP64 and optional electric holding brake

DIRECT-2-finger parallel gripper swivel module with smoothly running base jaw guidance on roller bearings

Integrated torque motor for high torque and flexible use by controlled position, velocity and torque

Integrated torque motor for high torque and flexible use by controlled position, velocity and torque

Control via digital IO for easy commissioning and rapid integration into existing systems

Large central hole for feeding through cables and hoses

Extremely flat design for minimal mounting surfaces and use in confined spaces

Virtually no wear parts no high machine availability and low operating costs

Compact design for minimal mounting surfaces and use in confined spaces

Measure pitch measuring system for less programming effort and time saving when commissioning and in operation

Low space requirement thanks to the compact merging of rotary axes and grippers

I		
2.5 ... 10	1.4 ... 32	0.06 ... 0.11
140 ... 2300	150 ... 600	
2.7 ... 10.8	2.4 ... 23.8	0.15 ... 1.2
6.6	5.52	0.00018
up to 0.03	up to 0.03	1
SSD	560	26
1.2 ... 1.8	2.95 ... 6.5	1.5
	25 ... 92	
E	8	
1	0	
40	40 ... 5%	20
Indemnity	Absolute measuring system INFRONIC® DIFFERENTIAL 2004 and 84995-CLW	
> 360°	> 360°	20 ... 270
		15 ... 140
		3 ... 5
		0 ... 0.55
		0.03 ... 0.22
		50

Integrating	Integrating	Integrating
External	External	Integrated
Beckhoff, Siemens*	Beckhoff, Siemens*	Integrated



Linear modules & axis systems

For positioning and motion tasks or for any other kind of automation for handling processes, SCHUNK offers the diversity of linear technology from a single source. Different types of standard modules can be combined into a complete system. A wide range of variants is available for both the drive and the guide concept.

The advantages of SCHUNK linear modules and axis systems

- **Flexible and extensive combinations** with different drive concepts
- **Over 25 years of experience in the field of linear technology**
- **Extensive axis system portfolio** with more than 450 standard components; pneumatic and electric
- **Extensive consulting service** ranging from choosing the appropriate axis technology to design tasks
- **Pre-assembled units for minimum installation effort** and immediate commissioning (incl. commissioning support)

High number of variants

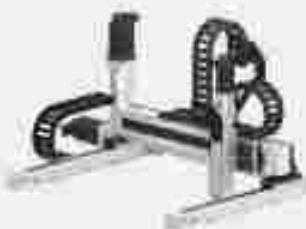
Pneumatic linear axes



Electric linear axes



Axis systems



Application examples



Separating of circuit boards



Automatic change of grinding wheels



Assembly automation



Handling of electronic components



Handling of gears



Assembly of gears

Pneumatic linear modules		
Universal linear module		
	UN	RUN
Description		
Linear module with pneumatic drive and pre-lubricated crossed roller bearings, free travel play in prism rails		Linear module with pneumatic drive and ball bearing guide
Advantages		
Closed slide construction for high rigidity		Double bearing of the guide shafts in the ball bearings for high load absorption and repeat accuracy < 0.005 mm
Shock absorbers and proximity switches integrated in the projecting surfaces for vibration-free movements and end position monitoring		Shock absorbers and proximity switches integrated in the projecting surfaces for vibration-free movements and end position monitoring
Compact dimensions for maximal mounting compact in the entire system		Heavy-duty sized guide shafts
Technical data		
Number of slides	5	5
Number of positions	1	1
Repeat accuracy (mm)	up to 0.01	up to 0.01
Nominal stroke length	0 ... 410	0 ... 300
Max. driving force (N)	753	753
Max. load weight (kg)	0.54 ... 15.81	0.5 ... 13.7
Adjustable end positions	Yes	Yes
Max. end positions adjustments per slide (mm)	25	25
Type of guide	Junction Miller guide	Ball bearing guide
High number of variants	+++	++
Required maintenance	Hydraulic shock absorbers, lubrication of the guide, replacement of seals	Hydraulic shock absorbers, lubrication of the guide, replacement of seals
Remark	Optionally available with up to two intermediate positions and with rod lock	Optionally available with up to two intermediate positions, rod lock and dustproof version
Slide type		
Plastic side cylinders	●	●
Aluminium cylinder		
Additional Characteristics		
Clean	●	●
Easyly disassembled		●
Extremely strong		○

● = fully supported ○ = technically possible
+ = standard-sized selection ++ = wide selection +++ = very wide selection

Compact slide CLM	Stroke module SLM	Linear axis PAP
		
Linear module with optimized length, with pneumatic drive and pre-loaded crossed roller bearings, free from play	Stroke module with optimized length, with pneumatic drive and pre-loaded crossed roller bearings, free from play	Linear axis with integrated pneumatic drive cylinder and pre-tensioned recirculating ball-bearing guides, free from play
Crossed roller guide design and solid construction ensures high load bearing capacities and end position accuracy in all installation positions	Crossed roller guide design and solid construction ensures high load bearing capacities and end position accuracy	High moment load bearing capacity through the use of high-performance profiled rails
Pre-loaded junction roller guides and therefore free from play	Pre-loaded junction roller guides in all installation positions, therefore free from play	High axis rigidity thanks to special extruded profile geometry
High load bearing capacity in all directions	High load bearing capacity in all directions	A ground surface ensures high precision and surface quality of the base jaws as well as an increased service life
6	6	7
t	1	1
up to 0.51	up to 0.01	0.04
0 ... 150	0 ... 150	0 ... 1700
682	487	250
0.07 ... 5.73	0.5 ... 5.8	1 ... 66.75
Yes	Yes	Yes
25	25	50
Junction roller guide	Junction roller guide	Double profile rail guide
•	•	•
Hydraulic shock absorbers, lubrication of the guides, replacement of seals	Hydraulic shock absorbers, lubrication of the guide, replacement of seals	Hydraulic shock absorbers, lubrication of the guide, replacement of seals
Optionally available with rod lock	Optionally available with rod lock	Optionally available with bellow, several intermediate positions and cable track
•	•	•
•	•	•

Electric linear modules

Linear modules & axis systems

Bosch linear modules

Linear direct axes

Compact linear module

ELM



Compact linear module

ELM



Slider module

ELM



Description

Electric linear module with direct drive: Stroke-stepper drive with linear direct and integrated controller, back-tension-free, pre-loaded roller guides

Stroke-stepper drive with linear direct drive and ball roller guides

Compact slider module with linear motor and roller guidance

Advantages

Control via digital I/O for easy commissioning and rapid integration into existing systems

Speed of retraction and extension can be adjusted in ten increments for high flexibility in the cycle time

For almost wear-free use and a long service life

Integrated motor and measuring system in the axis minimize incorporating contours and space requirements

Can be upgraded with absolute path measuring system for less programming effort and cost savings during commissioning and in operation

High dynamics for shorter cycle times resulting in high productivity

Almost no wearing parts for long service life and reliability of the system

No mechanical play between the drive elements for fast response and high positioning accuracy

Low vibrations and high holding force for the shortest positioning times and process stability

Technical data

Number of axes	1	1	1
Repeat accuracy (mm)	±0.01	±0.01	±0.01
Max. useful stroke (mm)	200	125	200
Max. driving force (N)	104	150	500
Max. speed (mm)	1000 mm/s	400 mm/s	400 mm/s
Max. acceleration (mm/s ²)	1000	400	400
Type of measuring system	Absolute or incremental	Absolute or incremental	Absolute or incremental
Type of guide	Junction roller guide	Junction roller guide	Scalor guide
Y-axis assembly	+-	+-	+-
Required connections	Multi-cavity flange	Cleaning of the magnetic track, lubrication of the guide	Cleaning of the magnetic track
Remark:	Stop position with mechanically adjustable stop positions, optimally matched with load balance	Freely programmable, especially suitable with rod lock, brake or load balance	Freely programmable, especially available with brake, limit switch, proximity switch, catch back, supported profile

Drive type

Synchronous servos			
Stepper servo drive			
Rack and pinion drive			
Direct drive (linear motor)	•	•	•

Motor & controller

Model	Integrated	Integrated	Integrated
Drive controller	Integrated	Rosch RAYBOT, Siemens®	Rosch RAYBOT, Siemens®
Interfaces	Signal I/O	Siemens M, Ethernet/IP, EtherCAT, PROFINET, PROFIBUS DP, PowerLink, LANopen	Mult-Ethernet DeviceNet, PROFINET IO, Ethernet/IP, EtherCAT, PROFINET

Additional features

Clean	•	•	•
Easy commissioning			

• = fully supported

• = medium selection ** = large selection *** = very wide selection

* = Additional components available upon request

Universal linear axes

EDR

EDM

EDT

Flat linear axes

EFL



Universal linear axis with single X-profile, linear motor, and roller guidance

Universal linear axis with double X-profile, linear motor, and roller guidance

Universal linear axis with triple X-profile, linear motor, and roller guidance

Flat linear axis with linear motor and profile rail guidance

Almost no wearing parts for long service life and reliability of the system

Almost no wearing parts for long service life and reliability of the system

Almost no wearing parts for long service life and reliability of the system

Almost no wearing parts for long service life and reliability of the system

No mechanical play between the drive elements for fast response and high positioning accuracy

No mechanical play between the drive elements for fast response and high positioning accuracy

No mechanical play between the drive elements for fast response and high positioning accuracy

No mechanical play between the drive elements for fast response and high positioning accuracy

Low vibrations and high holding force for the shortest positioning times and process stability

Low vibrations and high holding force for the shortest positioning times and process stability

Low vibrations and high holding force for the shortest positioning times and process stability

Low vibrations and high holding force for the shortest positioning times and process stability

F

F

F

F

±0.01

±0.01

±0.01

±0.01

7700

7700

7700

7700

1000

1000

1000

100

A

A

A

A

Absolute or incremental

Absolute or incremental

Absolute or incremental

Absolute or incremental

Roller guide

Roller guide

Slider guide

Slider guide

**

**

*

Cleaning of the magnetic tracks

Readily programmable, optimally available with brake, limit switch, reference switch, cable track, supported profile

Readily programmable, optimally available with brake, limit switch, reference switch, cable track, supported profile

Readily programmable, optimally available with brake, limit switch, reference switch, cable track, supported profile

Readily programmable, optimally available with brake, limit switch, reference switch, cable track

Integrated

Bosch Rexroth, Siemens*

Mult-Ethernet Series II, PROFINET IO, EtherCAT®, EtherCAT®, PROFINET

Integrated

Bosch Rexroth

Mult-Ethernet Series III, PROFINET IO, EtherCAT®, EtherCAT®, PROFINET

Integrated

Bosch Rexroth, Siemens*

Mult-Ethernet Series III, PROFINET IO, EtherCAT®, EtherCAT®, PROFINET

Integrated

Bosch Rexroth, Siemens*

Mult-Ethernet Series III, PROFINET IO, EtherNet/IP, EtherCAT®, PROFINET

Basic linear modules		Mechanical axes	Universal linear module
Linear slide	Slide		Slide
Description			
Flat linear table with spindle drive and double-profiled rail guide		Universal linear module with optional toothed belt or spindle drive and various guiding options	
Advantages			
Adaptable drive concept for flexible actuation and easy integration into existing control concepts		Adaptable drive motor for flexible actuation and easy integration into existing control concepts	
Double-profiled rail guide for very high force and moment loads		Choice of toothed belts or spindle drives for optimum drive fit for the application	
Extremely flat design for minimal mounting clearance		Various guidance options for optimum adaptation to the application	
Technical data			
Number of slides	1	12	
Repeat accuracy (mm)	±0.01	0.01 max. 0.08**	
Max. useful stroke (mm)	2540	7720	
Max. driving force (N)	10000	10000**	
Max. speed (m/s)	2.5	8	
Max. acceleration (mm/s²)	30	60	
Type of measuring system	Mosfet-dependent	Mosfet-dependent	
Type of guide	Double-profiled rail guide	Double-profiled rail guide	
Variant survey	++	+++	
Required maintenance	Lubrication of the guide and the spindle	Lubrication of the guide and, if necessary, the spindle; replacement of the cover tape	
Remark	Fully programmable, optionally available with customer-specific motor, limit switch and reference switch	Fully programmable, optionally available with customer-specific motor, limit switch and reference switch	
Drive type			
Spindle drive	●	●	
Toothed belt drive		●	
Rack and pinion drive		●	
Brushless drive (motor brush)		●	
Motor & controller			
Motor	Adaptable	Adaptable	
Drive controller	Mosfet-dependent	Mosfet-dependent	
Interface	Controller-dependent	Controller-dependent	
Ambient conditions			
Dust	●	●	
Electrolytically conductive	●	●	

● = fully supported

++ = medium selection +++ = large selection

+++ = extremely large selection

* = Additional possibilities available upon request ** = Depending on the drive type

Flat linear module

Series



Flat linear module with optional toothed belt or spindle drive.

Extremely flat design for minimal mounting clearance.

Double-profiled rail guide for maximum rigidity and precision in the application.

Choice of toothed belt or spindle drive for optimum drive for the application.

Universal linear module

Series



Toothed belt or rack and pinion driven universal linear module with closed profile and double-profiled rail guide.

Adaptable drive motor for flexible actuation and easy integration into existing control concepts.

Choice of toothed belt or rack-and-pinion drive for optimum drive for the application.

Double-profiled rail guide for very high force and moment loads.

Dimensions

up to 60.03**

F700

L2000**

S

G0

Motor-dependent

Double-profiled rail guide

Lubrication of the guide and, if necessary, the spindle. Replacement of the clear tape.

Freely programmable, optionally available with customer-specific motor, limit switch and reference switch.

Dimensions

up to 10.03

F700

G000

S

G0

Motor-dependent

Double-profiled rail guide

Lubrication of the guide and (if necessary) the gear rack.

Freely programmable, optionally available with customer-specific motor, limit switch and reference switch.

Adaptation

Motor-dependent

Customer-dependent

Adaptation

Motor-dependent

Controller-dependent

Pick&Place unit

PPU-E



Description

Compact, 2-axis unit for a fast, flexible running of any curve on one plane.

For the rapid and precise transfer or automated press-in operation of workpieces in high-speed assembly.

Advantages

High reliability and long service life of the system, as there is no longer strain due to moving masses and moving motor cables.

High productivity due to low cycle time.

Maximum flexibility in the application, as both axes can be controlled and regulated independently from each other.

Technical data

Number of axes	2
Horizontal stroke in Y [mm]	0 ... 750
Horizontal stroke in X [mm]	0 ... 150
Vertical stroke [mm]	0 ... 150
Travel angle (°)	0 ... 5
Nominal load [kg]	0 ... 5
Repeatability X-axis [mm]	±0.01
Repeatability Z-axis [mm]	±0.01
Repeatability, rotary (°)	
Dead weight [kg]	15 ... 75
Max. cycle times/Sec. [per minute]	110
Control	Sequential controller
Protection class IP	40
Type of guide	Standard bar guide
Number of possible combinations	
Variation variety	++

Motor & controller

Motor	Integrated
Drive controller	Stoch Seeman, Germany*

Options/Accessories

Ball lock	*
Center position	
Integrated valve	
Additional C-axis	*
Other package	

Product specifications

Drop	*
Easy installation	

* = fully supported

** = medium selection *** = large selection

* = additional controllers available upon request



Line gantry with a horizontal, linear, toothed belt axis, and a vertical, electric spindle axis

Area of application: To easily conduct the most common two-dimensional handling and assembly tasks for medium-sized and heavy workpieces

Maximum flexibility in application, freely programmable in the plane

Optimum running smoothness due to the use of high-quality linear axes with precision profiled rail guides

Easy and fast product selection due to pre-defined parameters

2
500 ... 1500

100 ... 500

0 ... 20

10.00
10.02

Rack gantry with two electric toothed belt axes in a horizontal direction, and one electric spindle axis in a vertical direction

Area of application: To easily conduct the most common three-dimensional handling and assembly tasks for medium-sized and heavy workpieces

Maximum flexibility in application, freely programmable in the plane

Optimum running smoothness due to the use of high-quality linear axes with precision profiled rail guides

Easy and fast product selection due to pre-defined parameters

2
500 ... 1500

500 ... 1500

100 ... 500

0 ... 20
10.00
10.02

Connectable via external motor

40

Profiled rail guide

90

Adaptable

Bachmann, Geometra*

Connectable via external motor

40

Profiled rail guide

110

Adaptable

Bachmann, Geometra

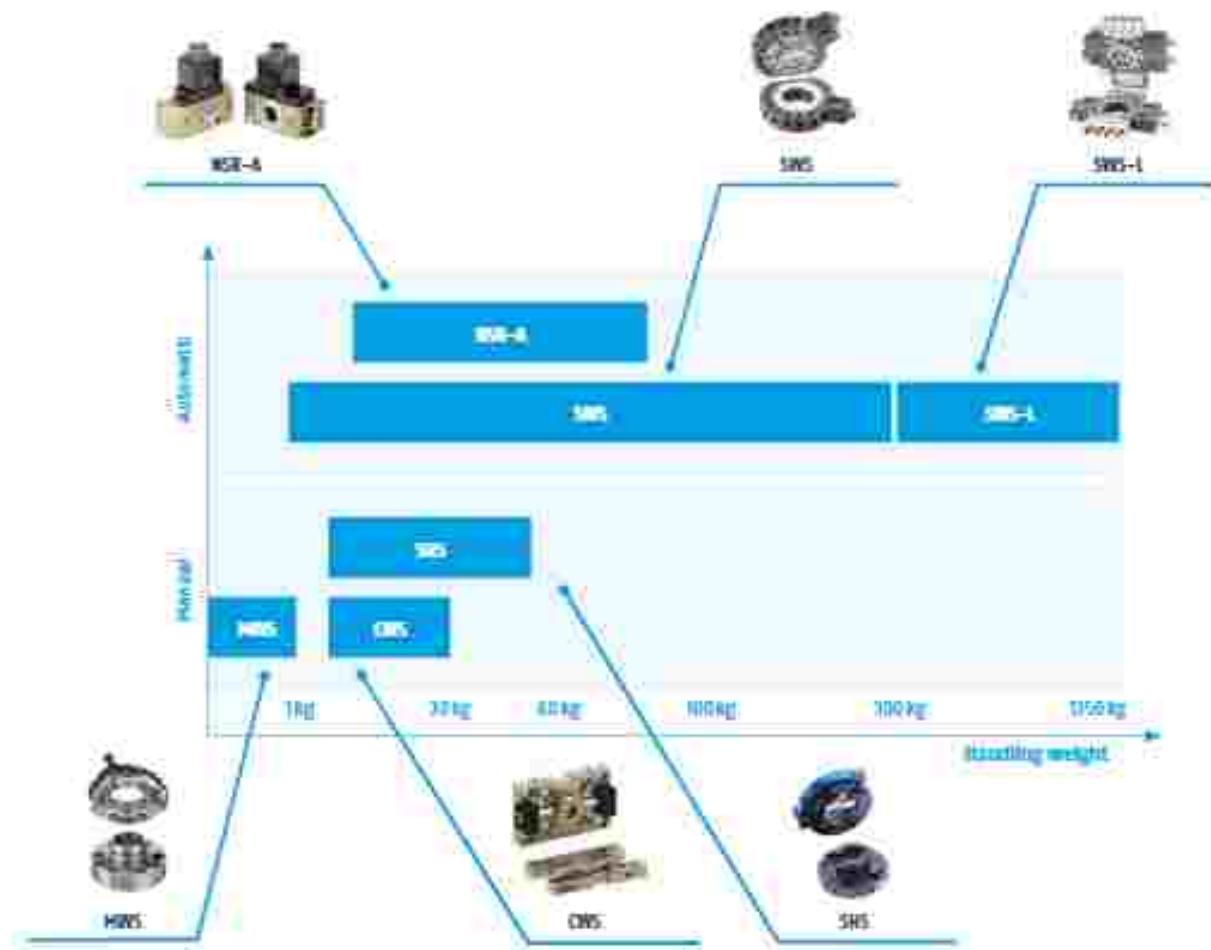


Change systems

By using SCHUNK change systems for robots, at their front ends, you increase the flexibility, efficiency, cycle rate and process reliability of your application. Grippers, tools, and other effectors are changed fast with the help of automatic and manual change systems. In the field of automation, SCHUNK also offers the most comprehensive portfolio of components for robot applications, from small components to heavy load handling.

Increase your productivity with SCHUNK change systems

- **Six different series** for the optimum solution to your application case
- **Maximum flexibility** due to a load range of 0 - 1050 kg
- **Proven and safe locking mechanisms** for fast and reliable tool changes
- **Extensive range of feed-through modules** and accessories for a comprehensive complete solution from a single source



Automatic change systems

SWS / SWS-L

- Patented fail-safe locking mechanism
- No-touch-locking® for simplified teaching
- All functional components made of hardened steel for high bearing load capacity of the change system
- Suitable storage racks for all sizes

Manual Change Systems

SHS

- Compact, reliable and intuitive system for convenient manual change without tools
- Perfectly suited to flexible production of products with a large range of variants
- ISO flange pattern for simple assembly on most types of robots without additional adapter plates

NSR-A

- Pneumatic pallet change system with patented locking
- Extremely compact design for space-saving changing and direct coupling on the machine table

CWS

- compact, manual change system with integrated air feed-throughs for the most important SCHUNK gripping and compensation modules
- Flat and weight-optimized through direct assembly of the gripper on the change system without an adapter plate

MWS

- Miniature change system – perfect for use in micro-systems technology, particularly for handling tiny components
- Extremely flat design for minimal interfering contours

Application examples



Scanning of battery round cells



Automated gripper change



Automated gripper change



Automated machine loading

Quick-change systems

SWS

SWS-L

SWS-A



Description

Pneumatic tool change system with patented locking mechanism and up to ten integrated air feed-throughs for pneumatic grippers.

Pneumatic tool change system with patented locking system for heavy loads up to a handling weight of 4000 kg.

Pneumatic pallet change system with patented locking and 4000 kg maximum moments.

Advantages

Complete series with 14 sizes for optimum selection of sizes and a wide range of applications.

Patented self-sustaining locking system for a reliable connection between the quick-change head and the quick-change adapter.

Saved time due to automatic pallet change.

Patented self-sustaining locking system for a reliable connection between the quick-change head and the quick-change adapter.

Manual emergency unlocking possible via counter-forces from springs.

Extremely compact design for space-saving changing and drives mapping on the machine table.

Manual emergency unlocking possible, no counter-forces from springs.

All functional components made of hardened steel for high bearing load capacity of the change system.

Multi-fit, patented locking system with self-locking and high locking force.

Technical data

Number of sizes:

15

4

7

Recommended handling weight [kg]:

0 ... 100

0 ... 1350

7

Moment load May [Nm]:

2.8 ... 7110

7600 ... 33500

75 ... 600

Moment load Mo [Nm]:

3.85 ... 3800

8000 ... 36200

200 ... 3600

Repeate accuracy [mm]:

up to 0.01

0.003

0.02

Dead weight [kg]:

0.05 ... 9.7

7.3 ... 23

0.4 ... 1.5

Screwed flange on the robotic:

Adapter plates/direct mounting

Adapter plate/offset mounting

Adapter plates

ISO 9009

ISO 9009

ISO 9009

Product features

Manual rotation:

●

●

●

Pneumatic actuation:

●

●

●

Locking maintaining position:

●

●

●

No possible moment loss possible:

●

●

●

Pneumatic energy transmission:

●

●

●

Electric energy transmission:

●

●

●

Ambient conditions

Dust:

●

●

●

Corrosive environment:

●

●

●

High temperature and humidity with version on request:

●

●

●

● = fully supported

Manual change systems

SAS

SBS

HHS



Manual tool change system with integrated air feed-through, locking monitoring, and optional electric feed-through.

Compact, manual change system with integrated air feed-throughs for the most important SCHUNK gripping and compensation modules.

Manual tool change system with integrated air feed-through and optional electric feed-through.

Series with six sizes for optimum selection of tools and a wide range of applications.

High productivity through fast manual gripper changes, especially with small and medium-sized fix sizes.

Extremely flat design for minimal interfering contours.

Integrated pneumatic feed-through for secure energy supply of the handling modules and tools.

Fast and weight-optimized through direct assembly of the gripper on the change system without an adapter plate.

Simple handling without additional tools; can easily be detached anytime by using the handle.

The locking lever is opened to the side, allowing the change to be operated easily even in confined spaces.

Series with five sizes for optimum selection of tools and a wide range of applications.

Optimal space for feed-through air hoses, cameras, laser beams, etc.

6	5	7
0 ... 58	0 ... 38	0 ... 1
63 ... 960	10 ... 160	0.5 ... 1
173 ... 2321	10 ... 200	0.2 ... 0.75
0.02	0.01	0.1
0.2 ... 4	0.07 ... 0.445	0.007 ... 0.016
Mounting	Adapter plates	Adapter plates
BD-9405		

6	5	7
0 ... 58	0 ... 38	0 ... 1
63 ... 960	10 ... 160	0.5 ... 1
173 ... 2321	10 ... 200	0.2 ... 0.75
0.02	0.01	0.1
0.2 ... 4	0.07 ... 0.445	0.007 ... 0.016
Mounting	Adapter plates	Adapter plates
BD-9405		

6	5	7
0 ... 58	0 ... 38	0 ... 1
63 ... 960	10 ... 160	0.5 ... 1
173 ... 2321	10 ... 200	0.2 ... 0.75
0.02	0.01	0.1
0.2 ... 4	0.07 ... 0.445	0.007 ... 0.016
Mounting	Adapter plates	Adapter plates
BD-9405		

Feed-through modules

Safe and reliable tool change also includes safe and reliable control and supply of the changed tools. That is why the SCHUNK SVO feed-through modules are the perfect complement to the SCHUNK SWS, SWS-L, SHS and NSR-A change systems. From simple signals to welding currents, a wide range of tools can be supplied. In addition, various modules are available for the implementation of pneumatics, fluids, vacuum and hydraulics.

Benefit from SCHUNK Implementation modules

- **Perfect for easy combination**
with any size of SCHUNK change system
- **Wide range of variants**
for feeding through various electric and fluid media
- **Combination of several option modules**
for maximum flexibility of the change system
- **Minimum wear for a high number of change cycles**
and a long service life
- **Complete solution available from a single source**
with cable plugs, cable extensions and protective covers

Application examples



Use of a signal module for safe feed-through of sensor signals



Controlling electric, detouring spindle ECE

Feed-through modules for change systems SWS, SHS and NSR-A

The SWO-E and SWO-F series can be easily attached to the change systems either directly or via adapter plates. Suitable modules are available for all change system sizes.

Electrical feed-through modules SWO-E

Over 50 standard modules for the implementation of:



Signals



Communication



Performance



Servo signals

Fluid feed-through modules SWO-F

Over 20 standard modules for the implementation of:



Pneumatics



Digital



Vacuum



Hydraulics

Feed-through modules for the heavy load range

Special feed-through modules are also available for the SWS-L heavy-load changer series. Above all, these are characterized by the option of safe unlocking and locking, as well as larger (volume) flows. Any module in the normal series can also be used on SWS-L with adapter plates.



Modules from the SWO-L-E series for signal transmission and control of the change system.



Modules from the SWO-L-F series for the passage of fluids and hydraulics

Rotary feed-throughs

With SCHUNK rotary feed-throughs, the feed-through of electrical signals and pneumatics for use in stationary applications and on robots is child's play – even with endless rotation. The rotary feed-throughs are optimally designed for the torque moments occurring with the new robot generation. Particularly developed long-lasting and smoothly running seals permit the use of small and economical drives.

Reliable execution of electrical signals and pneumatics

- For robot applications and rotary indexing tables
- Rotary feed-throughs facilitate endless rotation without hoses and cables twisting around the axis.
- **Combined pneumatic and electric feed-through** for comprehensive supply of gripping systems and tools
- **Safe energy transfer even at higher speeds** thanks to slip ring contacts

Application examples



Industrial packing



Toolholder balancing



Product packaging labeling

Rotary feed-through		Stationary rotary feed-through	
BRF 2	BRF SE		
			
Description			
For feeding through electric signals and pneumatics for use on robots even when they are endlessly rotating at a maximum RPM of 120		For feeding through electric signals and pneumatics for stationary use	
Advantages			
Combined pneumatic and electric feed-through for comprehensive supply of gripping systems		Combined pneumatic and electric feed-through for comprehensive supply of gripping systems	
ISO flange (zero) for simple assembly in most types of robots without additional adapter plates		Standardized shaft and the easy assembly of grippers	
Complete series with 12 sizes for optimal size selection		Attaches up to 500 RPM, even at fast endless rotations of up to 500 RPM, a reliable supply of pneumatic and electrical power for your gripping system is ensured	
Technical data			
Number of sizes	12	2	
Recommended workpiece weight [kg]	0 ... 250		
Max. speed [RPM]	0 ... 120	300 ... 500	
Continuous torque [Nm]	0.5 ... 22	1 ... 13	
Starting torque (after startup) [Nm]	0.1 ... 25	1 ... 20	
Max. handle force F _c [N]	160 ... 3500	2000 ... 4000	
Max. impact force F _i [N]	2000 ... 18000		
Moment M _x , M _y [Nm]	15 ... 350	50 ... 180	
Moment M _z [Nm]	10 ... 600		
Pneumatic energy consumption	2 ... 4	4 ... 8	
Electrical energy consumption	4 ... 10	6 ... 11	
Dead weight [kg]	0.25 ... 2.2	1.2 ... 4	
Product features			
continuous rotary motions	•	•	
Screwed flange acc. to ISO 9409 size standard	•		
Pneumatic energy harvesting	•	•	
Vacuum energy harvesting			
Electric energy harvesting	•	•	
bus technology			

● = fully supported

Compensation units

Connecting, assembling, inserting, loading and unloading workpieces are everyday challenges of automation. To prevent damage to tools or workpieces, SCHUNK compensation units with compensation in all six degrees of freedom ensure the necessary flexibility between the robot and the tools, for example. This avoids system malfunctions caused by imprecise tolerances and increases process reliability.

More process stability with SCHUNK compensation units

- **Seven different series –**
optimally adapted for your application
- **Units for tolerance compensation**
available in all six degrees of freedom:
- **Centric reset for a defined position of the components**
after the compensation process
- **Various sensor options for increased process reliability**
and simplified commissioning
- **Customer-specific solutions**
for particularly heavy workpieces or tolerance compensation in the horizontal plane, for example

Compensation in every direction



XY compensation



Z-axis compensation



Rotational compensation



Angular compensation

Application examples



Packaging of product packaging



Loading a lattice



Raw material handling



Handling of motor blocks

Compensation units

Compensation units

Compensation units

ACE-1

ACE-3

ACE-2



Description

Compensation unit with rotational and angular compensation, allowing the end effector to fully adapt to the component position.

Compensation units with X/Y compensation with up to 4 mm compensation length.

Compensation unit with Z-axis compliance with up to 16 mm compensation path.

Advantages

Designed to offer rotation and angle compensation for inaccuracies in component position and saves time, cost and effort through reduced robot programming effort.

Smooth guidance for high moments made with minimal space requirements.

Locking for right switching of the unit at a defined extended or retracted position.

Central reset enables a defined position for the components.

Central locking for centering the unit in a defined position.

Compact design for minimum installation height.

Spring-supported return of the unit, adjustable via compressed air for optimum deflection.

Pneumatic position memory for eccentric locking in retracted position.

Can be combined with ACE-3/4 without additional adapter plate.

Technical data

Number of sizes	1	2	3
Compensation stroke X/Y (mm)	±2.7	±2.5 .. ±4	
Compensation stroke Z (mm)	6.3		8 .. 10
Rotary compensation [°]	±8	±17 .. ±18	
Actuating force [N]			30 .. 120
Return force 2 at 6 bar in extended position [N]			500 .. 1500
Return force 2 at 6 bar in retracted position [N]			100 .. 1450
Unit weight [kg]	0.6	0.46 .. 1.5	0.55 .. 1.7
Locking force at 6 bar [N]		225 .. 520	
Maximum payload [kg]	0 .. 5	0 .. 12	
Vertical payload [kg]		0 .. 15	0 .. 12
Repeat accuracy [mm]		0.1	0.07
Locking force F _z [N]		214 .. 520	280 .. 1500
Max. tensile force F _x [N]		300 .. 750	400 .. 500
Max. contact force F _y [N]		1700 .. 3200	200 .. 1500
Moment load capacity M _x , M _y (Nm)	6.3	16 .. 30	10 .. 30
Torsion torque M _z (Nm)	2.4	3.5 .. 9	70 .. 80
Angular compensation x [°]	3°		
Angular compensation y [°]	3°		
Angular compensation z [°]			

Product features

Positional locking	●	●	●
Position memory		●	
Screwed flange acc. to ISO 9409 standard	●	●	●
Mounting via proximity switch	●	●	●

Ambient conditions

Humidity	●	●	●
Dust contamination	●		
High-temperature version on request		●	●

● = fully supported

ACE-S

ACE-F

Tolerance compensation unit

TOI



Compensation unit series XY and Z-axis compensation with up to 12 mm compensation path



Compensation unit with XY compensation and integrated spring return for a handling weight of up to 37 kg



For compensation of smaller position deviations with up to 2° maximum deflection for assembly and handling applications

Three compensation directions in one unit, compact design for minimal height

Spring return to three spring positions for a defined centric position at a repeat accuracy of 0.02 mm

Compensation of workplace-related tolerances and position inaccuracies reduces the risk of jamming; necessary assembly forces are reduced and wear of the workplace and handling device is minimized

Centric locking for right switching of the unit to a defined centric position

Direct assembly of grippers means there is no need for additional adapter plates

Direct assembly of grippers means there is no need for additional adapter plates

Pneumatic position memory for economic locking in deflected position

Junction roller guide for smooth compensation at low compensation forces

Compact design, low height and weight

4

34 ... 42

10 ... 14

240 ... 1100

800 ... 3000

6

41.5 ... 45

8

1 ... 1.5

2.5 ... 28.5

800 ... 2700

9 ... 200

9 ... 160

±1

800 ... 2700

110 ... 2000

500 ... 4000

10 ... 500

10 ... 750

0.1 ... 3.1

1 ... 32

0.01

100 ... 2800

200 ... 12000

1.5 ... 50

6 ... 150

0.1 ... 2.1

20 ... 800

up to 0.02

30 ... 800

5 ... 120

15 ... 160

±1 ... 7

±1

±1.2 ... 12

Collision protection

Collisions and overloads on the robot may cause damage to the tools, workpieces or the machines. In the automated handling process, the SCHUNK monitoring modules offers an effective instrument for process reliable production, and preventing expensive downtimes in production.

Process-reliable manufacturing with collision and overload sensors from SCHUNK

- Integrated monitoring for signal transmission without delay in case of collisions so that the robot can be stopped immediately
- Mechanical flexibility for compensation of the robot's reaction pathway in the event of a collision or overload
- Triggering force and torque can be adjusted via the operating pressure for optimum protection of your robots and components

Application examples



Pick&Place with magnetic grippers



Bin picking

Collision and overload sensors	
Manual reset	Automatic reset
6PS	6PR
Description	
For monitoring of robots and handling units in the event of collisions or overload conditions.	For monitoring of robots and handling units in the event of collisions or overload conditions from a detection force of 76 N.
Advantages	
Triggering force and torque can be adjusted via the operating pressure for optimum protection of your robots and components.	Automatic reset function for faster resuming of production after a collision.
Integrated monitoring for signal transmission without delay in case of collisions so that the robot can be stopped immediately.	Triggering force and torque can be adjusted via the operating pressure for optimum protection of your robots and components.
ISO adapter plates are optional for simple assembly on most types of robots without additional fastening tools.	Integrated monitoring for signal transmission without delay in case of collisions so that the robot can be stopped immediately.
Technical data	
Number of sizes:	4
Momentes M _y , M _x (Nm)	7.5...430
Triggering force F _t (N)	500...7000
Axial deflection (mm)	9.5...12
Angle deflection (°)	4...12
Rotary deflection (°)	45...280
Repeat accuracy (mm)	up to ±0.02
Operating pressure range (bar)	0.5...6.0
Net weight (kg)	0.4...7.0
Product features	
Programmable activation	•
Break-in spring optionally available	•
Working conditions	
Ozone	•
Electro-conductivity	•
Humidity	•

• = fully supported

Force/torque sensors

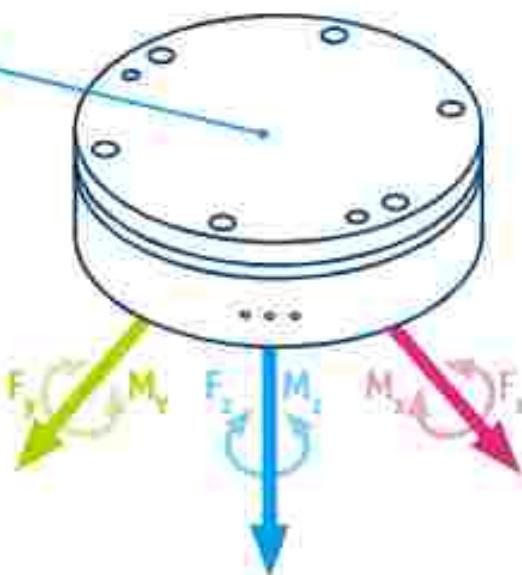
Where precise results are needed, force/torque sensors are in trend and provide robots with the required sensitivity. The sensors precisely detect the occurring process forces and transmit them to the control unit. This allows for highly precise correction of the robot path. The result are constant forces, and hence constant machining patterns.

The advantages of SCHUNK force/torque sensors

- **Rigid 6-axis force/torque sensors**
for precision measuring in all six degrees of freedom,
- **Universally applicable in robotic applications**
such as medicine, grinding, testing, inserting, and research and development
- **Silicon gauges provide a signal 75 times stronger than conventional foil gauges.**
this signal is amplified resulting in near-zero noise distortion.
- **Robust design due to a higher overload range**
for a long service life

Dimensions of forces and moments

The strain gauges (DMS) of the 6-axis force/torque sensors measure the strain applied in all six degrees of freedom (F_x , F_y , F_z , M_x , M_y , and M_z). The DMS signals are amplified in the sensor.



Application examples



Automated grinding of supply air chambers for stoves



Automated grinding with the vibro



Haptic measurements of vehicle components

6-axis force/torque sensors

FT-600

FTB



Description

6-axis force/torque sensors for high-precision measuring in all six degrees of freedom

Universally applicable in robotics applications such as grinding, inserting, and research and development

6-axis force/torque sensors for high-precision measuring in all six degrees of freedom

Universally applicable in robotics applications such as grinding, quality assurance, joining, robotics, medicine, and research and development

Advantages

Compact design due to space-saving set-up with integrated electronics

Up to two calibrations are available to ensure maximum flexibility in the process

Plug & Work directly compatible with KUKA and Universal Robots software module

Wide range of options with up to three different ranges of measurement per axis

Easy integration via Ethernet/IP optional Profibus as well as remote access via web server for easy configuration

Technical data

Number of axes	3	3
Calibration	SI-15-0...SI-4000-300	SI-13-0.12...SI-40000-6000
Calibration accuracy	Inspire	Alpha
Weight of sensor [kg]	0.1...1.5	0.01...4.5
Range of measurement F_x, F_y [N]	±75...±4000	±12...±40000
Range of measurement F_z [N]	±235...±8000	±17...±80000
Range of measurement M_x, M_y [Nm]	±6...±300	0.17...±6000
Range of measurement M_z [Nm]	±4...±300	0.17...±4000
Resolution F_x, F_y [N]	0.09...1.57	0.001...5.75
Resolution F_z [N]	0.34...1.57	0.003...18.7
Resolution M_x, M_y [Nm]	0.0012...0.07	0.00001...1.5
Resolution M_z [Nm]	0.0017...0.07	0.00001...0.75

IP protection class

Without IP protection	●
IP60	●
IP64	●
IP65	●
IP67	●
IP68	●

● = fully supported



6-axis force/torque sensors for high-precision measuring in all six degrees of freedom

Universally applicable in robotic applications such as grinding, quality control, joining, robotics, medicine, and research and development

Wide range of options with up to three different ranges of measurement per size

Integrated electronics from size Gamma

6-axis force/torque sensors for high-precision measuring in all six degrees of freedom

Universally applicable in robotic applications such as grinding, quality control, joining, robotics, medicine, and research and development

Wide range of options with up to three different ranges of measurement per size

Sensor system can be used with a wide range of DAQ Cards

16
SI-12-0.12 .. SI-16000-2000

PCI interface box (Sigma/Mini) or integrated from Gamma

0.01 .. 31.8

±12 .. ±16000

±17 .. ±17000

0.12 .. ±2000

0.12 .. ±7000

0.003 .. 4

0.001 .. 8

0.00001 .. 0.5

0.00001 .. 0.5

17
SI-12-0.12 .. SI-40000-6000

DAQ card (available separately)

0.01 .. 31.8

±12 .. ±16000

±17 .. ±17000

0.12 .. ±2000

0.12 .. ±7000

0.003 .. ±25

0.001 .. 16.7

0.00001 .. 1.5

0.00001 .. 0.75



REMENDO | Machining tools

With the new SCHUNK tools, a large range of machining steps that used to be manually performed, can now be automated. The result: Higher productivity, consistently perfect machining results, lower unit costs. Manual machining of workpieces with hand tools is also often associated with putting ergonomic strain on employees. In addition, health risks are often incurred due to fine particle emissions such as abrasive dust or chips.

Create added value with a changeover to robot-assisted machining

- Minimize health risks
- Consistent quality of the machining results
- Increased safety and ergonomic working conditions
- Reduction of the machining time
- Increase in machining capacity



Deburring

One of the classic finishing operations in the metalworking industry is the smoothing of sharp edges and the removal of burrs. However, manual deburring operations not only have low added value, they are also very monotonous and often lead to injuries. SCHUNK offers a wide range of tools for deburring with the robot – including one with a brushless electric motor.



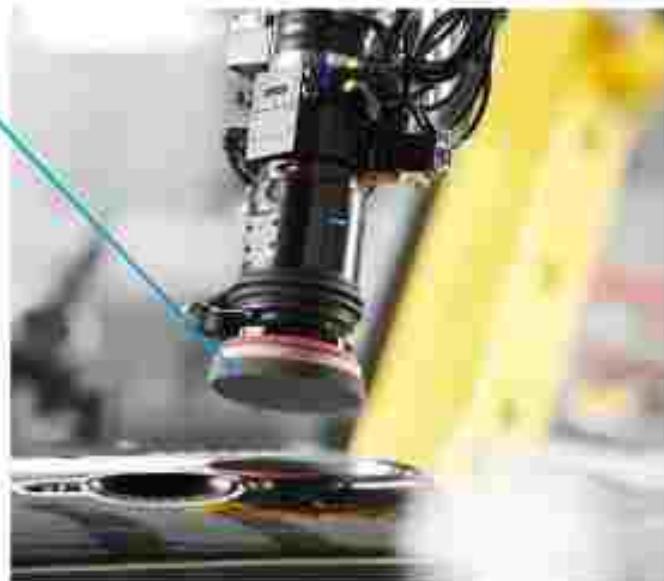
Grinding

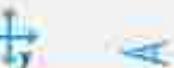
Grinding workpieces before polishing and finishing the surfaces is physically demanding and time-consuming. SCHUNK tools for automated grinding are ideally suited for uniform material removal from small and large-surface workpieces.



Polishing

Polishing is usually the final machining step. This gives the workpiece its finish. The contact force is decisive for the result. This should be constant and adapted to the application. With SCHUNK tools, workpieces can be automatically machined. The result: uniform surfaces for a perfect end result.



Deburring tools		Deburring spindles			
DRS	DRT	DRC	REC	RDS	
					
					
					
					
Description					
Flexible tool for deburring with the robust and proven deburring tools with radial compensation. Torque adjustable up to 25 N.	Pneumatically driven tile with radial compensation for machining workpieces operating at up to 12,000 RPM.	Pneumatic deburring tool with radial compensation for deburring workpieces operating at up to 10,000 RPM.	Secure deburring spindle with radial compensation and adjustable speed of rotation for machining workpieces operating at up to 50,000 RPM.	Flexible deburring spindle for use with rubber optimizing at up to 55,000 RPM.	
Advantages					
Adjustable rigidity of the tool for flexible use and ideal results with different materials.	The compensation force can be adjusted using compressed air for high-quality deburring results in any installation position.	The compensation force can be adjusted using compressed air for high-quality deburring results in any installation position.	Brushless electric motor for high efficiency, long service life and adjustable speed for more flexibility.	Variable high-frequency spindle for maximum flexibility for chambering, oil-free operation for increased cleanliness.	
Optional tool changing system for automatic changing of different deburring tools.	Flexible use on robotic arms or as a stationary unit.	Flexible use on robotic arms or as a stationary unit.	Variable speed control for the flexible machining of different workpieces with different tools and only one secure deburring tool.	Adjustable rigidity of the spindle via compressed air for clean chambering in any installation position.	
Use of proven deburring tools for simple automation of manual deburring processes.	Use of proven tiles for simple automation of manual deburring processes.	Rotating planet air engine with high torque for high feed rates and a reduced machining time.	The rigidity of the tool can be adjusted using compressed air for high-quality deburring results in any installation position.	High speeds for a high surface quality.	
Applications	Pneumatic	Pneumatic	Pneumatic	Electric	Pneumatic
Technical data					
Compensation	Radial & Radial	Radial	Radial	Radial	Radial
Number of axes/units	2	1	2	2	2
Power (W)			250 – 400	230 – 710	130 – 1540
Compensation path (mm)	±10 Radial ± 15° Radius = 25.75 Depth = 3.1067	±10	±7.1 – ±8.7	± 8.6 – ±7.5	±5 – ±5
Min/max. compensation force (N)	1500	1500	1500 – 7000	1500 – 7000	2116.7 – 78,446.7
Idle speed (RPM)	12000	30000 – 40000	13000 – 50000	25000 – 65000	25000 – 65000
Toolholder mounting	Tool holder for deburring tools: Type K, C, D, E, F	Tool holders Ø 35 mm	Collet (E=11) Ø 6, 8 mm	Collet (E=11) Ø 6, 8 mm	Collet Ø 35 mm
Gross weight (kg)	1.09 – 1.09	2.00	1.71 – 2.36	1.7 – 5.25	1.1 – 3.45

● = fully supported

Polishing spindles

MFT

MFT-B

Orbital sander tool

AV

Compensated unit

PCT



Flexible deburring spindle for use with robots



Flexible polishing spindle for use with robots operating at up to 5,600 RPM



Pneumatic polishing spindle with radial compensation, perfect for polishing and finishing workpieces operating at up to 5,600 RPM



Pneumatic orbital sander tool with axial compensation up to 12.7 mm for grinding and polishing workpiece surfaces



Pneumatic, axial compensation unit for flexible adjustment of compensation of pressure force

Axially flexible spindle in compact form for free-hand-to-hand places

Flexible high-frequency spindle for maximum flexibility for polishing

The rigidity of the tool can be adjusted using compressed air for high-quality deburring results in any installation position

Adjustable compensation by means of a double-action pneumatic cylinder for a constant cylinder load regardless of the orientation of the tool

Adjustable compensation by means of a double-action pneumatic cylinder for a constant contact force

Adjustable rigidity of the spindle via compressed air for clean machining in shy installation position

Adjustable contact force of the spindle via compressed air for clean surfaces in any installation position

Flexible use on robot arms or as stationary unit

Optional media change system for automated exchange of grinding or polishing wheels

Integrated path measuring system for monitoring and control of the process

Radial compensation with radial contact assures uncomplicated use, even for sensitive tools

Resisting pliers all angles with high torque

Resisting pliers all angles with high torque

Optional connection for suction air induced compensation and susceptibility to tools

Integrated weight force compensation for circumferential forces independent of the orientation of the tool, especially in robot-guided applications

Dimensions

Dimensions

Dimensions

Dimensions

Dimensions

Axial	Axial	Radial	Axial	Axial
1	2	1	4	3
250	390	390	1000	1000
46.1	47.5	47.1	12.7	12
1 - 25	9.7 - 45	9.4/10	0.0001 - 13.1868.7	0.0001 - 85.748
25000	5600	5600	0.0000	0.0000
	Quick-action chuck up to Ø 9.5 mm	Collet 6.8	Velco fastener	Ø 125-150 mm
0.51	1.3	4.37	2.68	2.54 - 3.63

Wherever you are located – SCHUNK is close to you!



Headquarters Lauterbach
SCHUNK GmbH & Co. KG
Spann- und Greiftechnik
Kahnstraße 106 – 136
D-7430 Lauterbach/Werra
Tel. +49-7133-901-0
Fax +49-7133-901-2099
info@de.schunk.com



Plant Backnang-Büren
SCHUNK GmbH & Co. KG
Spann- und Greiftechnik
Schloss-Wallstr. 12
D-7622 Backnang-Münster
Tel. +49-7122-700-0
Fax +49-7122-700-3099
info@de.schunk.com



Plant Wessig
TL.-O. SCHUNK GmbH & Co.
Spanntechnik AG
Lachlinger Str. 23
D-7635 Wessig
Tel. +49-7122-700-0
Fax +49-7122-700-3099
info@de.schunk.com



Plant St. Georgen
SCHUNK Electronic Solutions GmbH
Am Gänsehäufel 4
D-7760 St. Georgen
Tel. +49-7125-3000-0
Fax +49-7125-3000-5099
stgeorgen-02400@de.schunk.com



Plant Northville, USA
SCHUNK Inc., Inc.
20 Elby Court Drive
Northville, MI 48167, USA
Tel. +1-984-572-4705
info@us.schunk.com



Plant Aadorf, Switzerland
CRESSI AG
Schützenstr. 15
CH-8955 Aadorf
Tel. +41-52-365-91-10
Fax +41-52-365-91-11



Plant Elektrotech Düsseldorf
Gleisbachtal GmbH & Co. KG
Gleisbachtal 2
D-7630 Düsseldorf
Member of SCHUNK Lantech
Phone +49-7115-5000-0
Fax +49-7105-51802-209
info@elektrotech-schunk.de



Plant Casnigo, Italy
S.p.A. S.p.A.
Via Galileo Galilei 26
IT-21022 Casnigo (BG), Italy
Tel. +39-0363-54000
Fax +39-0363-54001

This way to all locations

The addresses and directions
planned are available for you.

schunk.com/locations →



Copyright

All text drawings and product illustrations are subject to copyright and are the property of Sennheiser GmbH & Co. KG or the corresponding licensee.

All rights reserved. In particular, any extraction, reprinting, distribution (including available to third parties) translation or image - including excerpts - of the material is prohibited and requires the prior written approval.

Technical changes

The data and dimensions in this catalogue are non-binding and only provide an approximate description. We reserve the right to make changes to the products delivered in accordance with the data and illustrations in this catalogue, e.g. in respect of technical data, design, fittings, material and general appearance.



SCHUNK GmbH & Co. KG
Spano- und Greiftechnik
Bahnhofstr. 106 - 134
D-76348 Lautern-Nieder
Tel. +49-7833-109-2599
schunk.com

Follow us:



We print sustainably.

